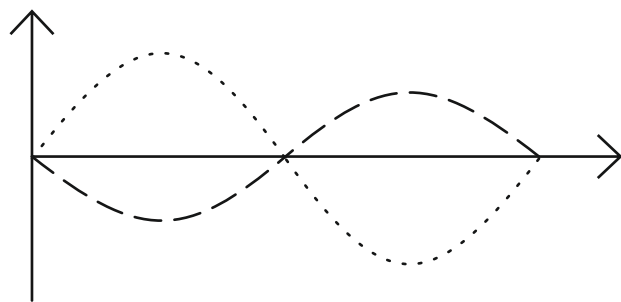
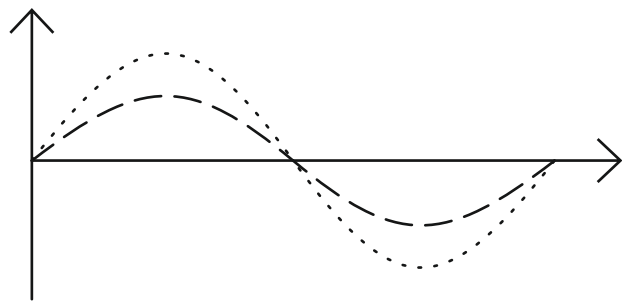
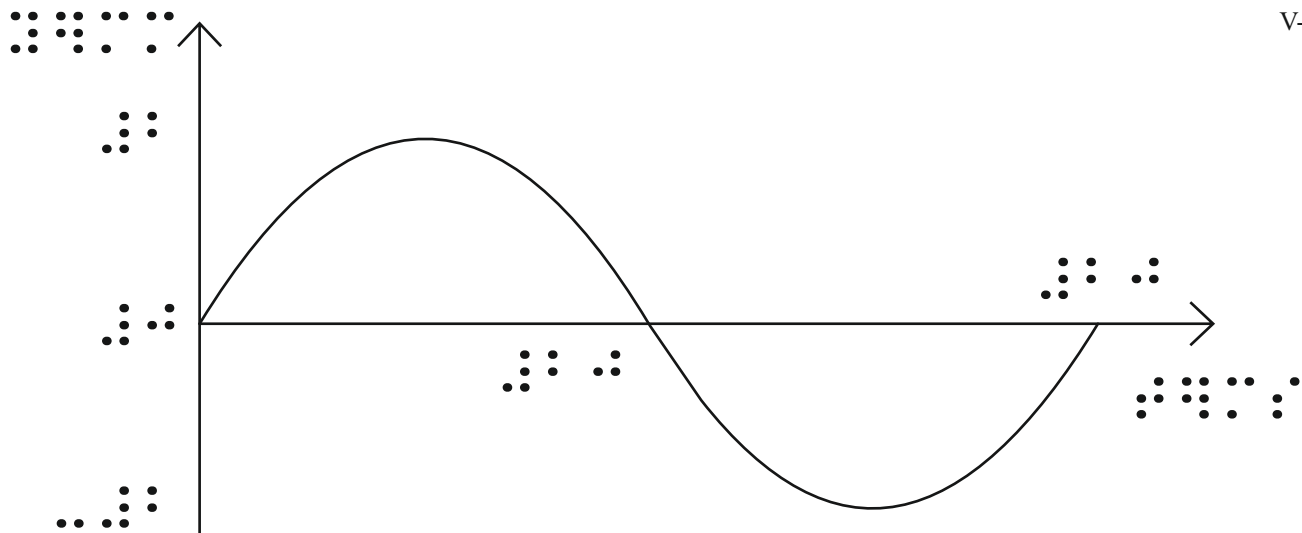


1-8

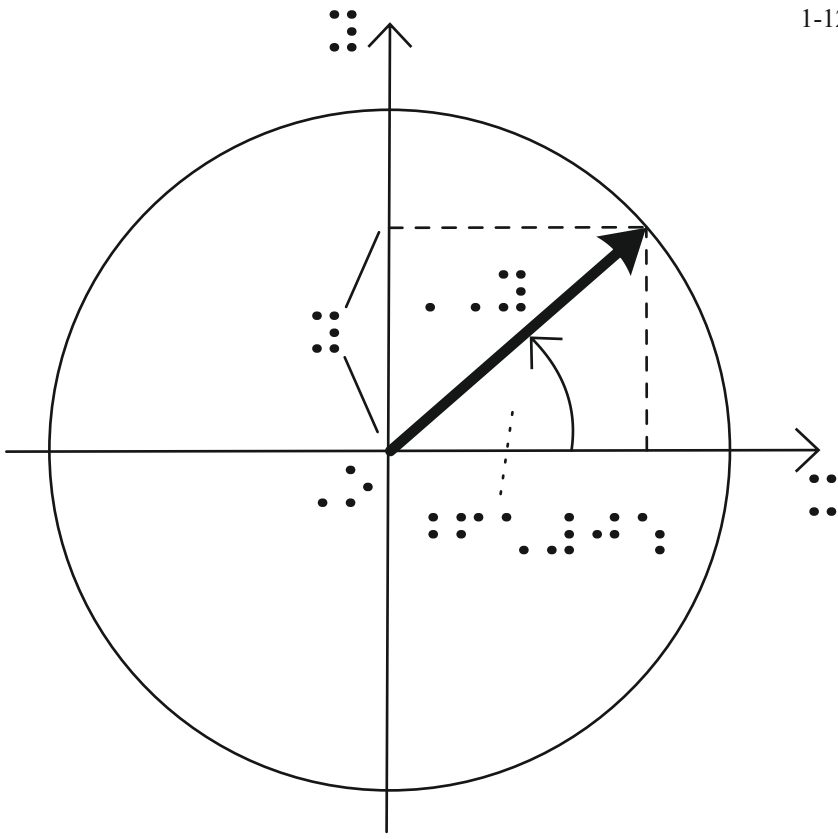


V-2

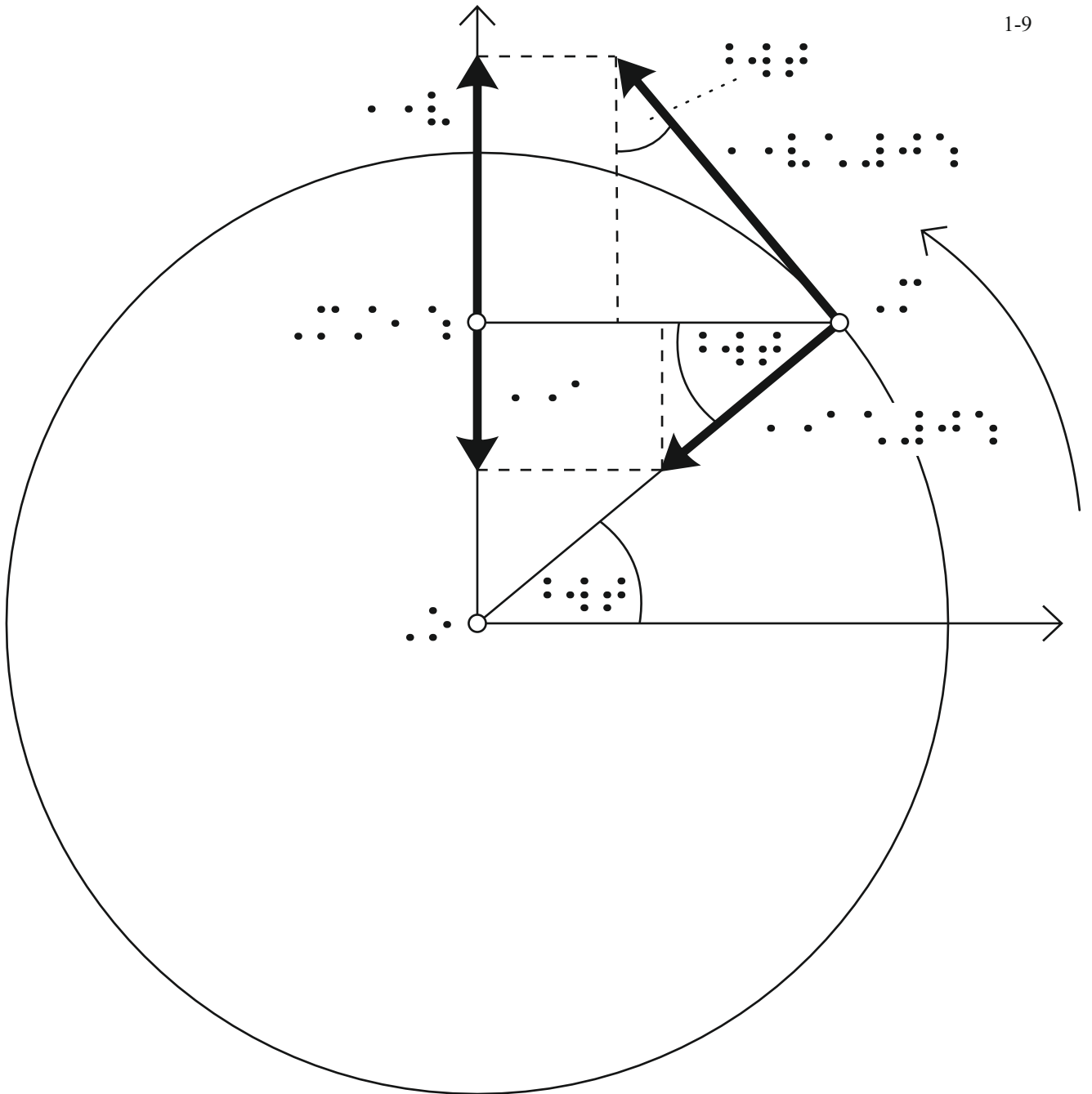


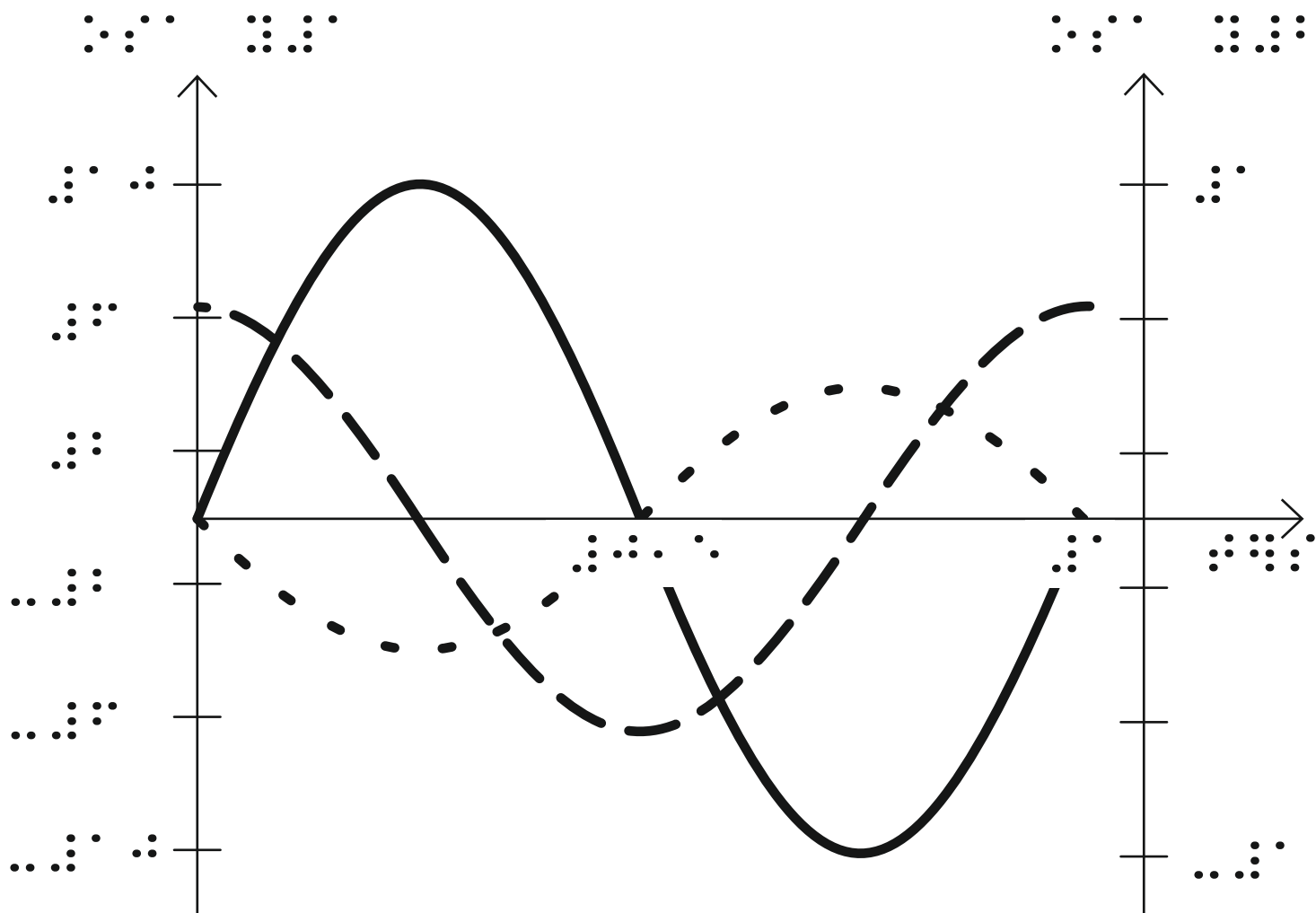
V-1

1-12



1-9

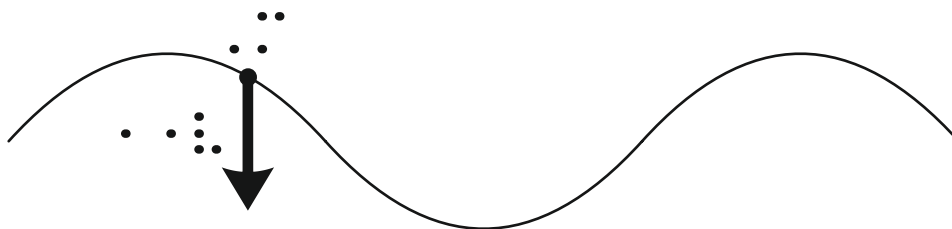




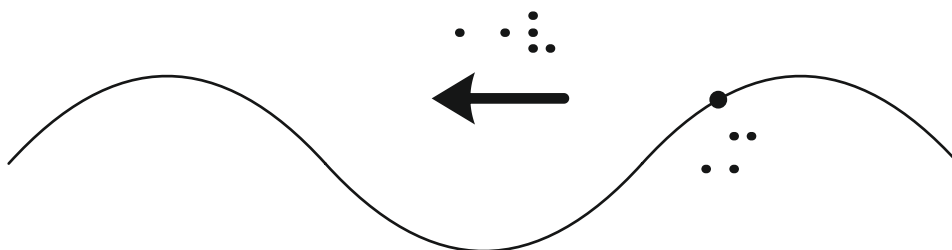
Braille text block containing multiple lines of Braille characters, likely representing a list or a series of instructions.

1-10

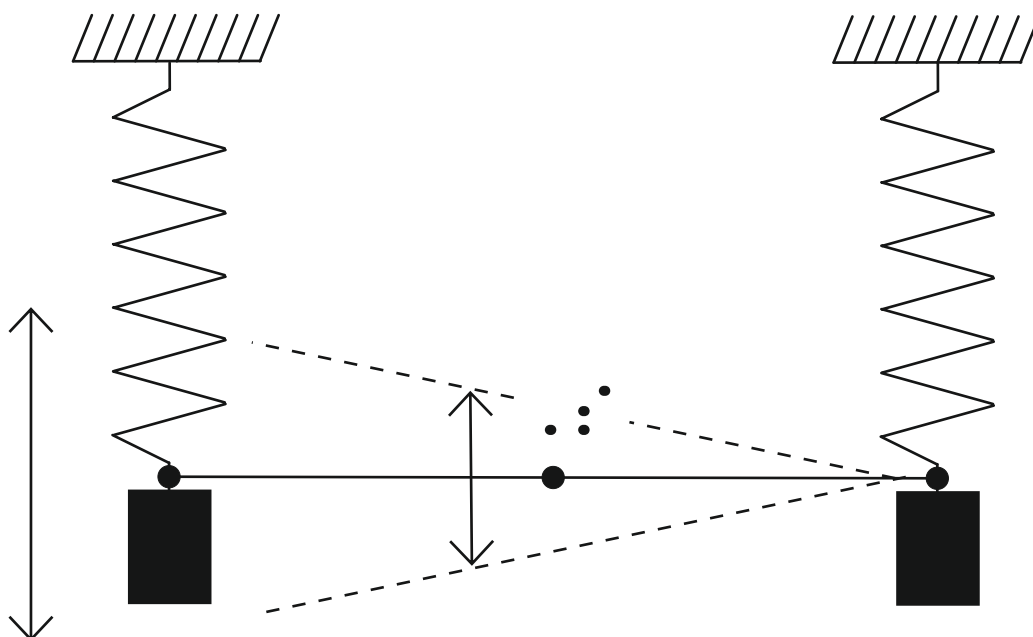
2-6



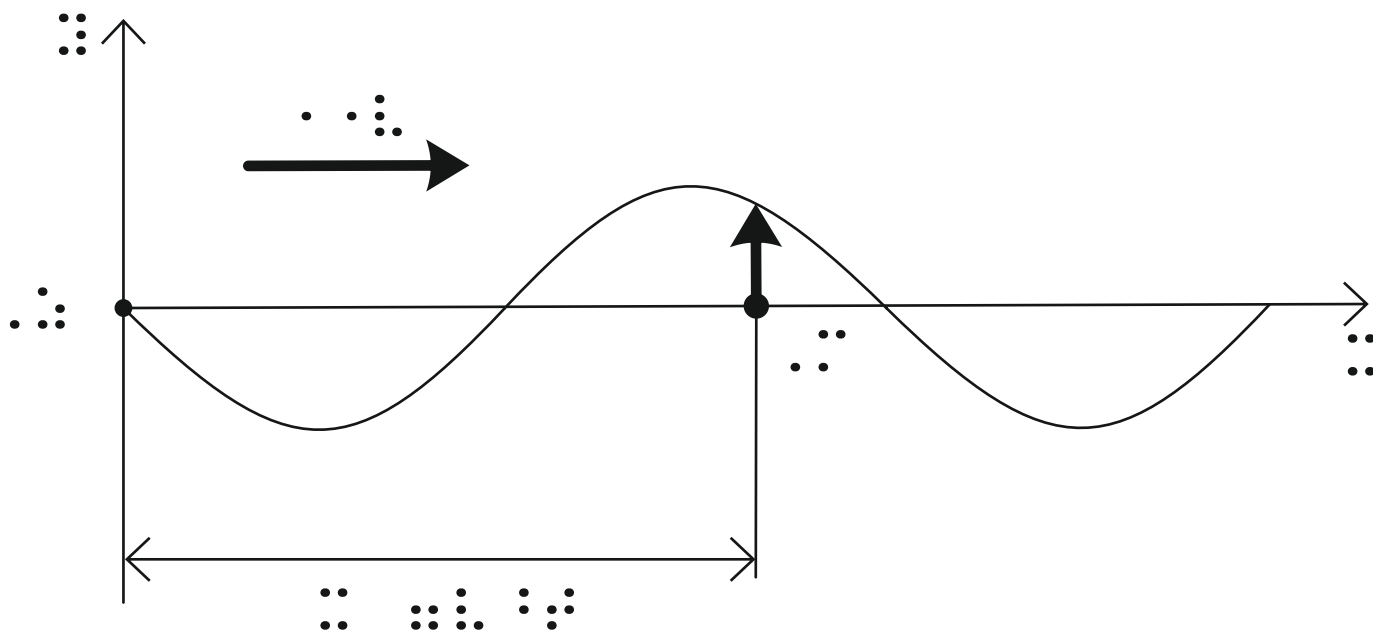
2-7

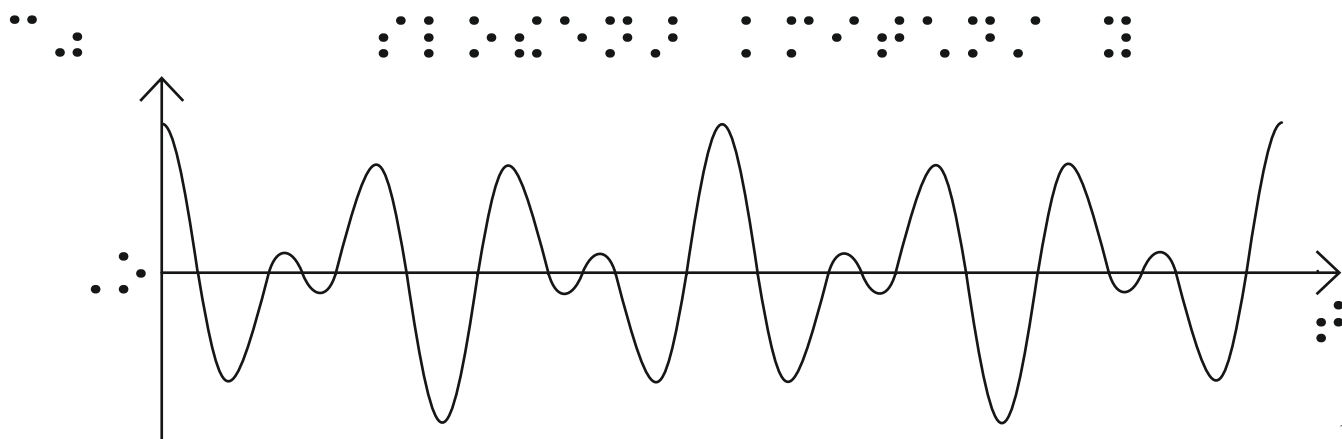
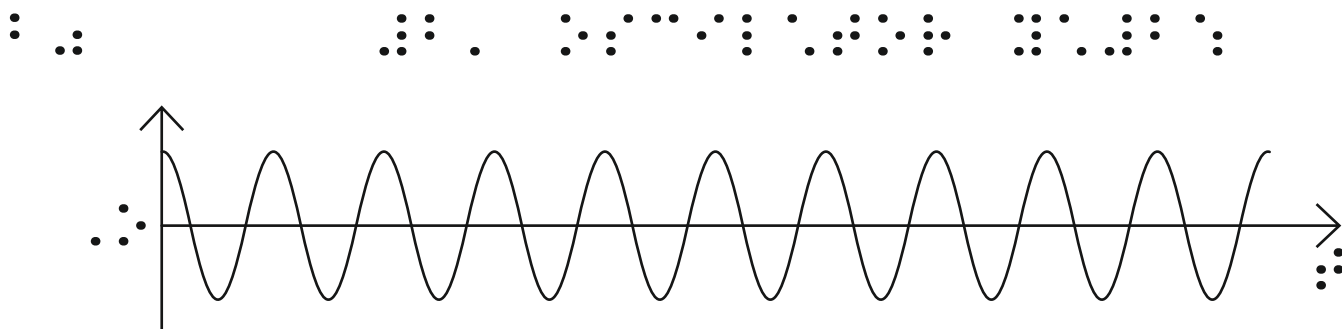
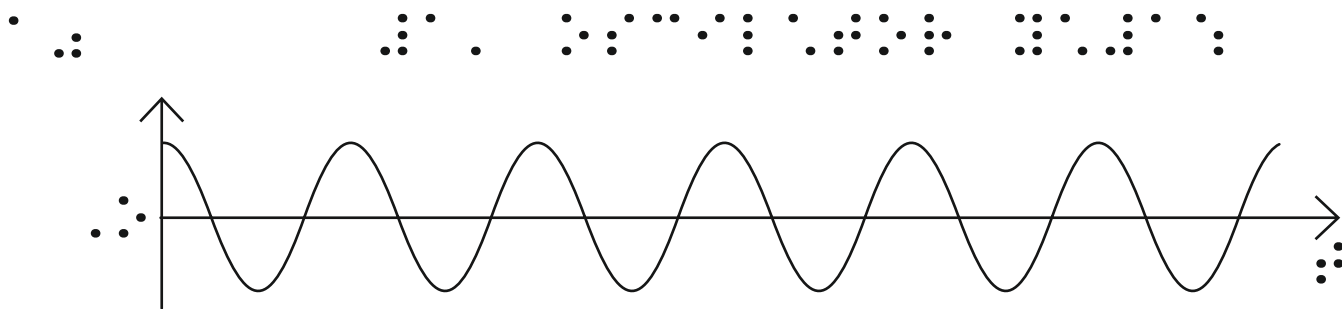


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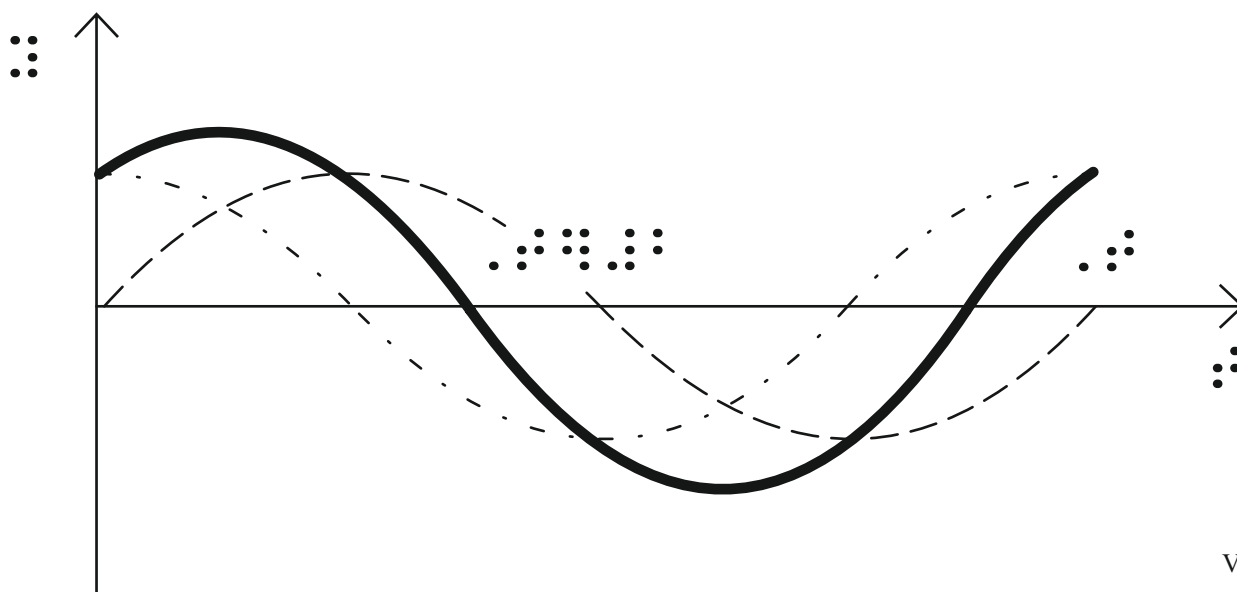


2-8

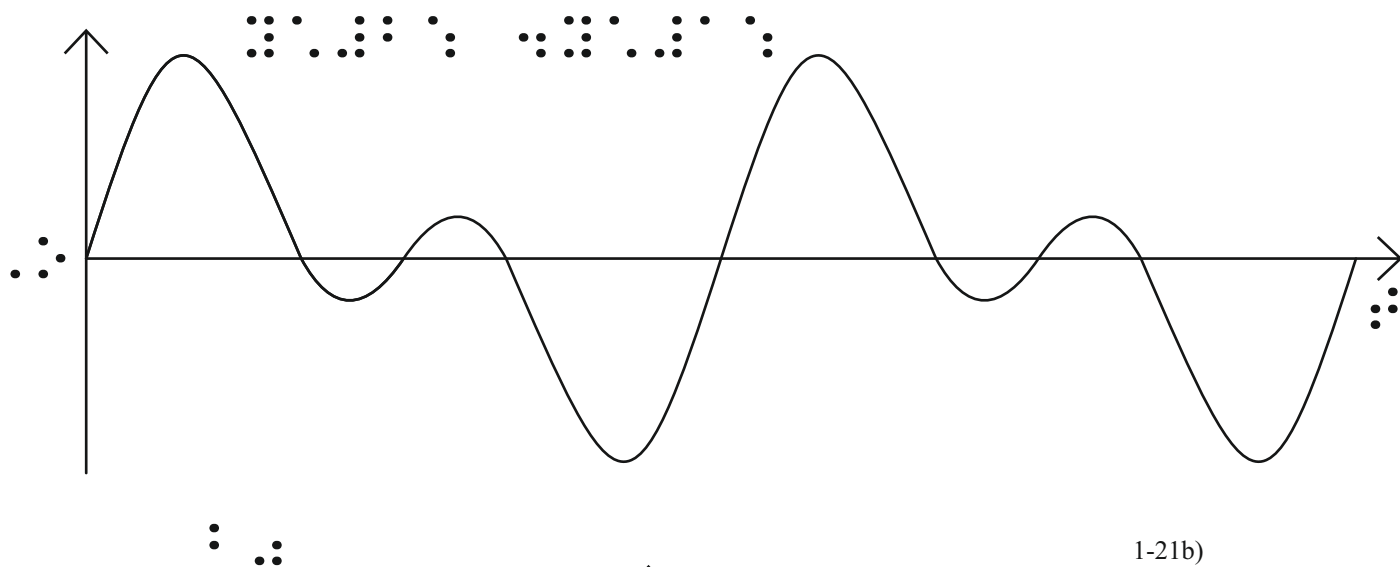
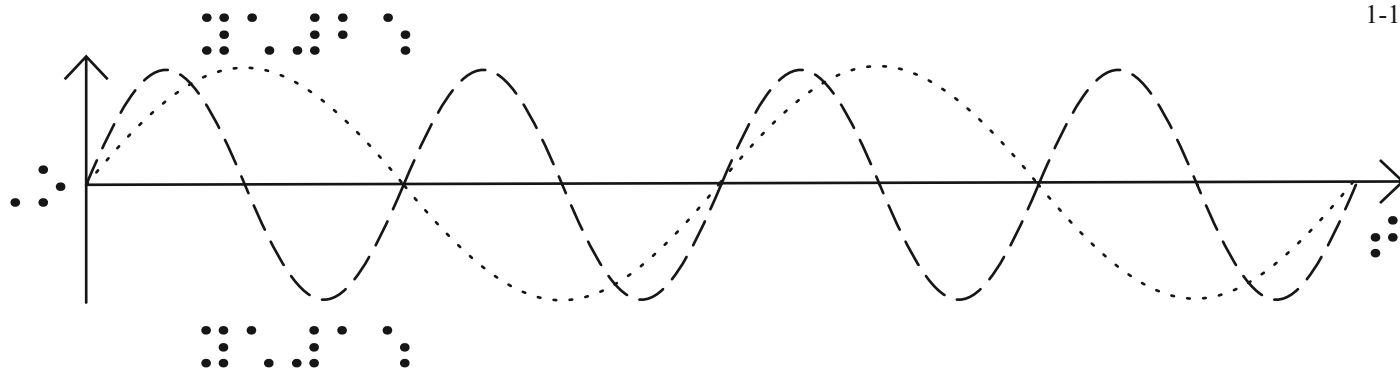




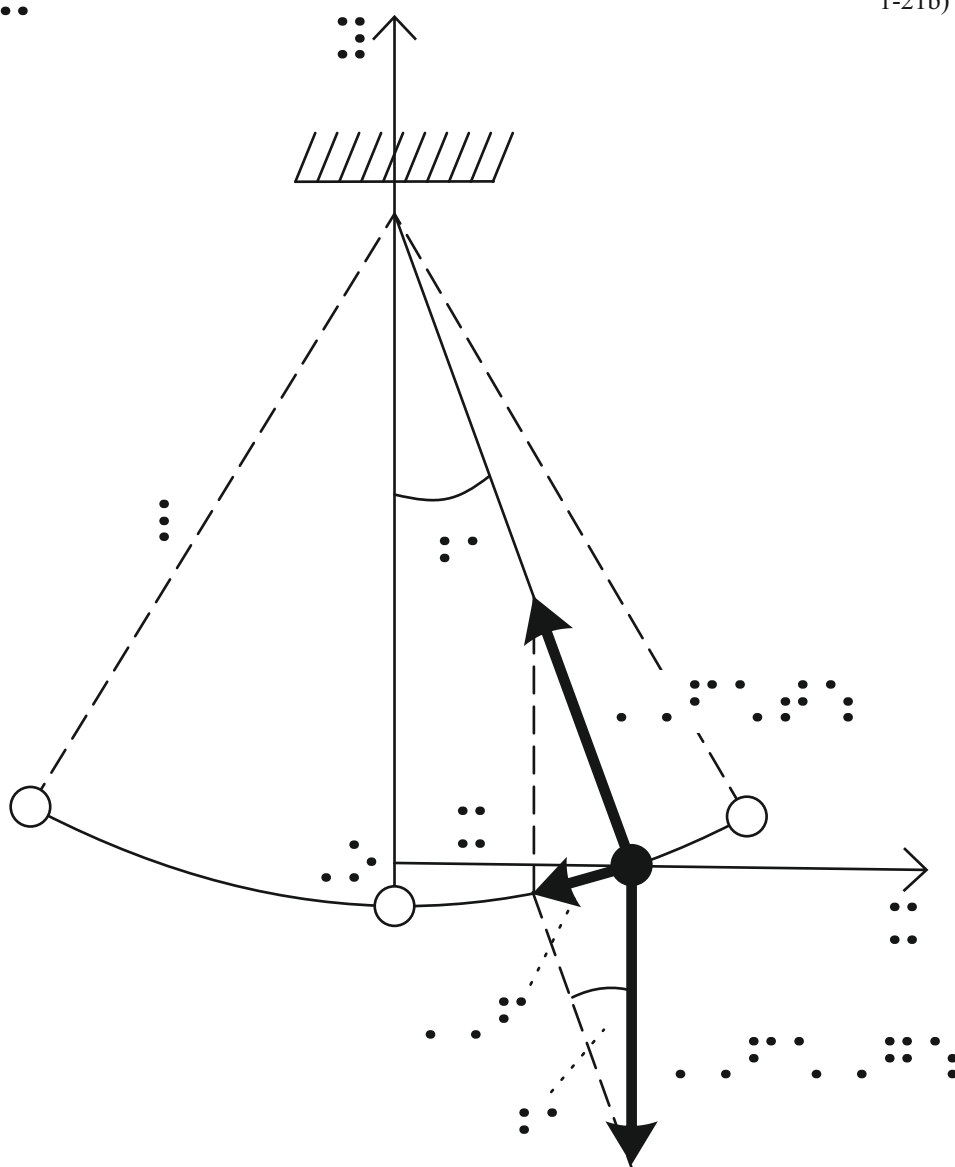
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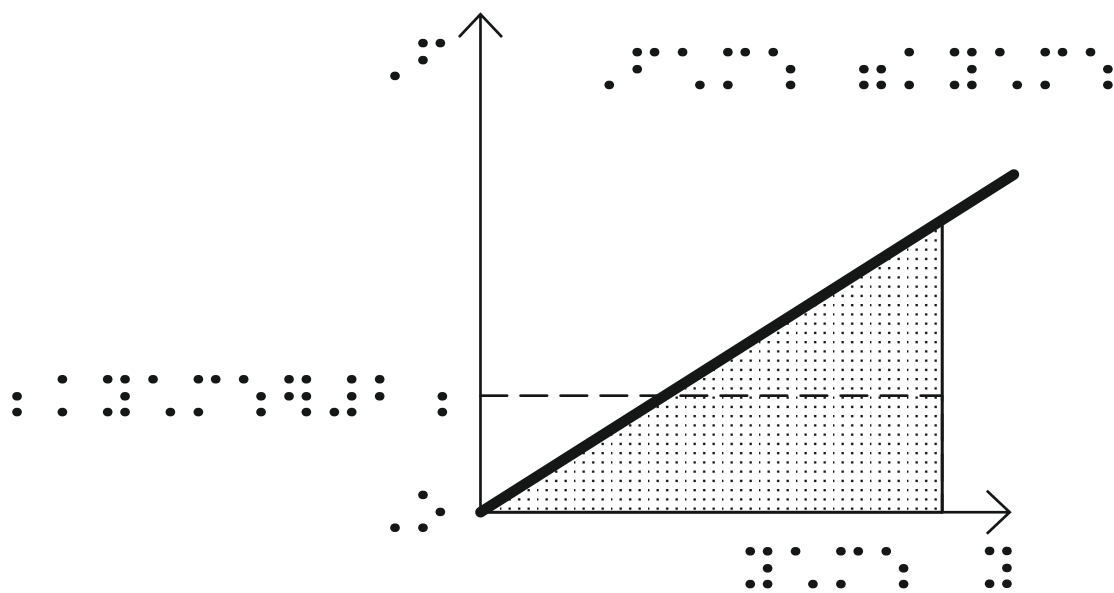
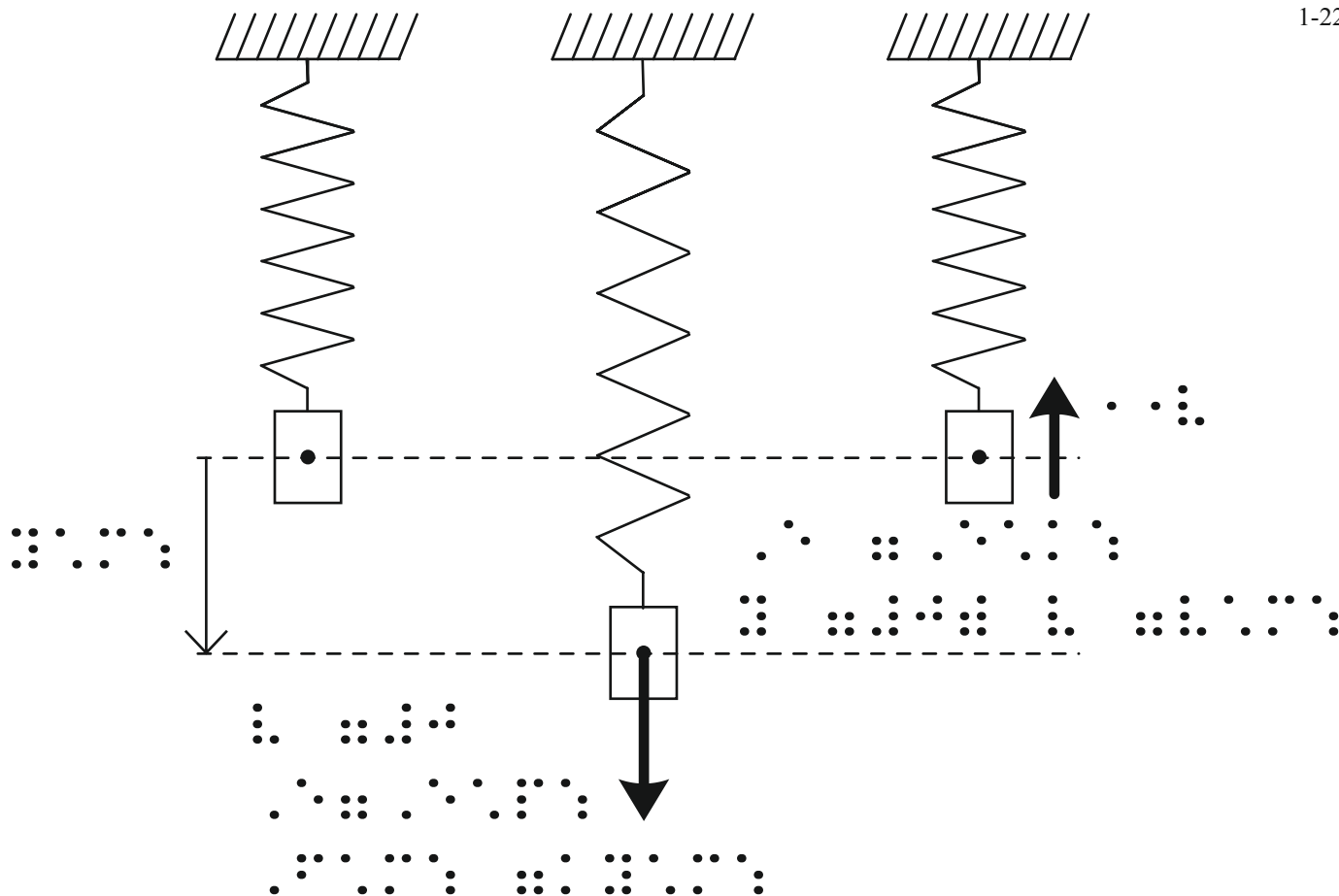


V-4

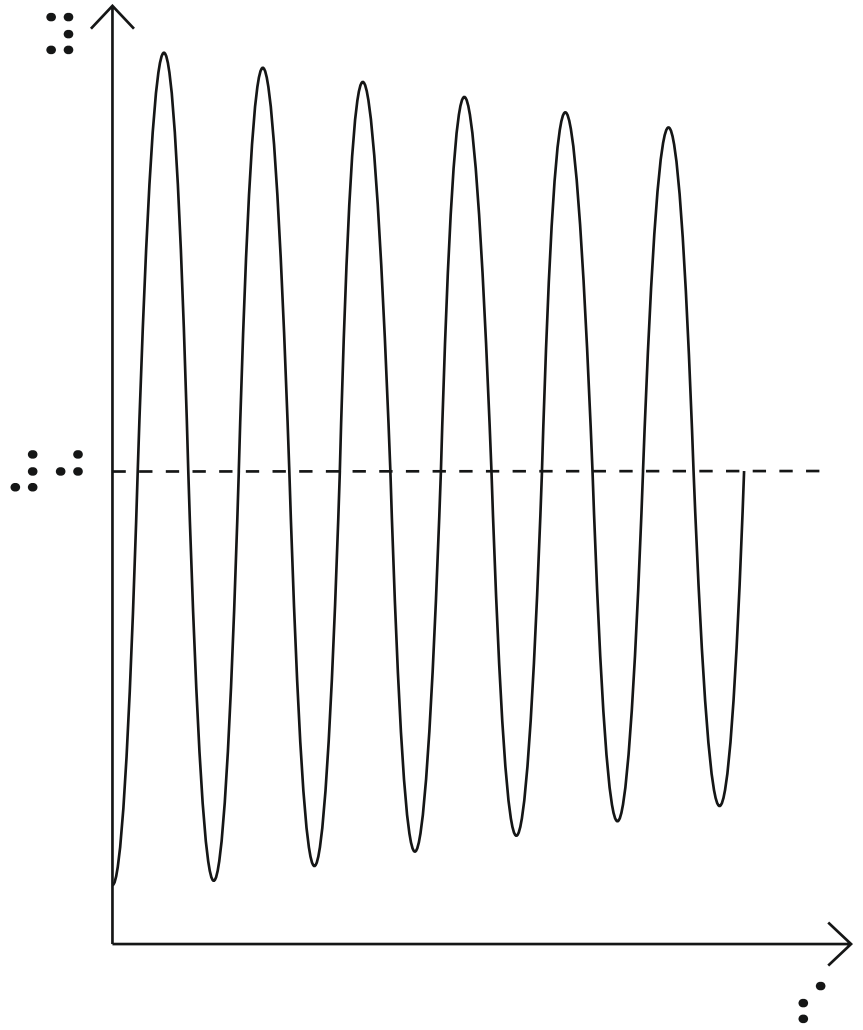
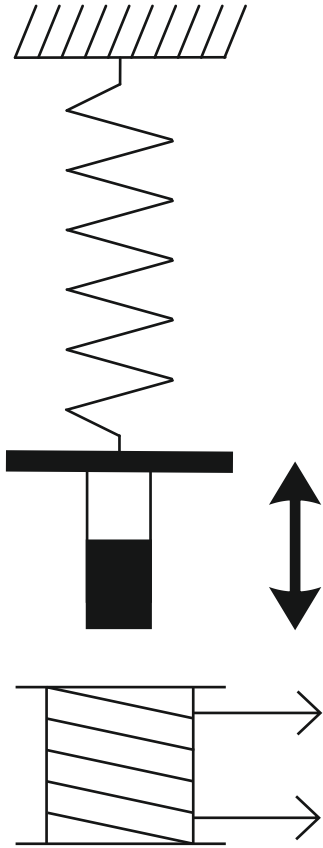


1-21b)

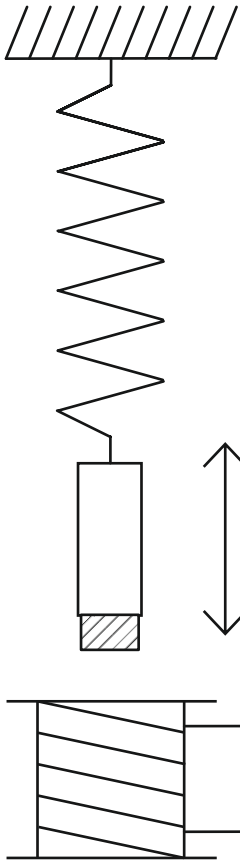




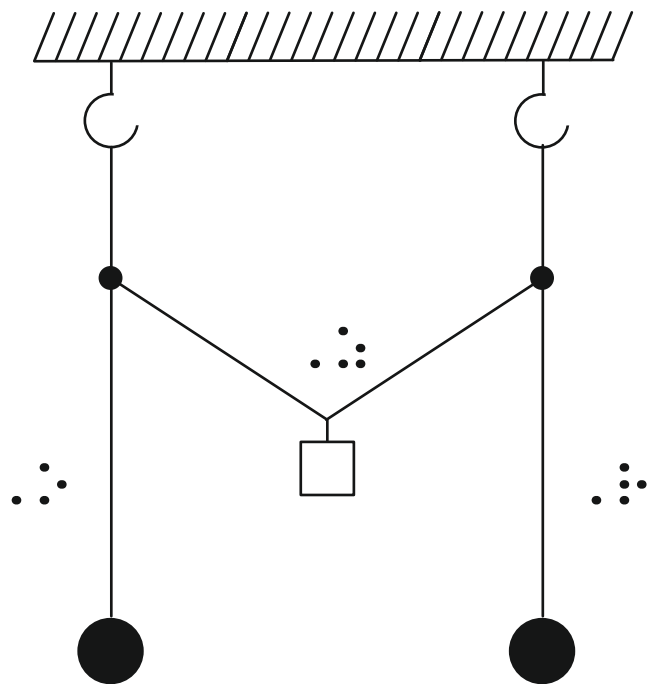
1-24

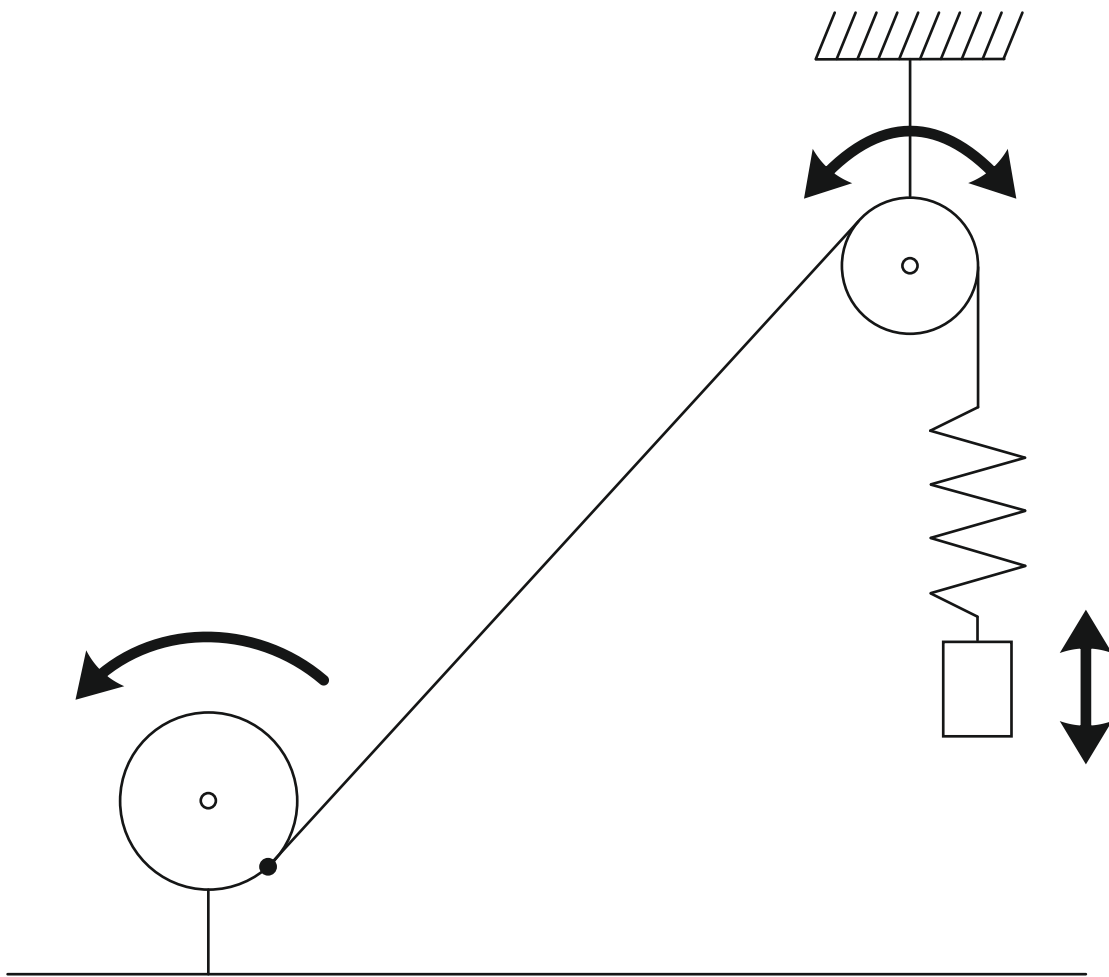


1-27



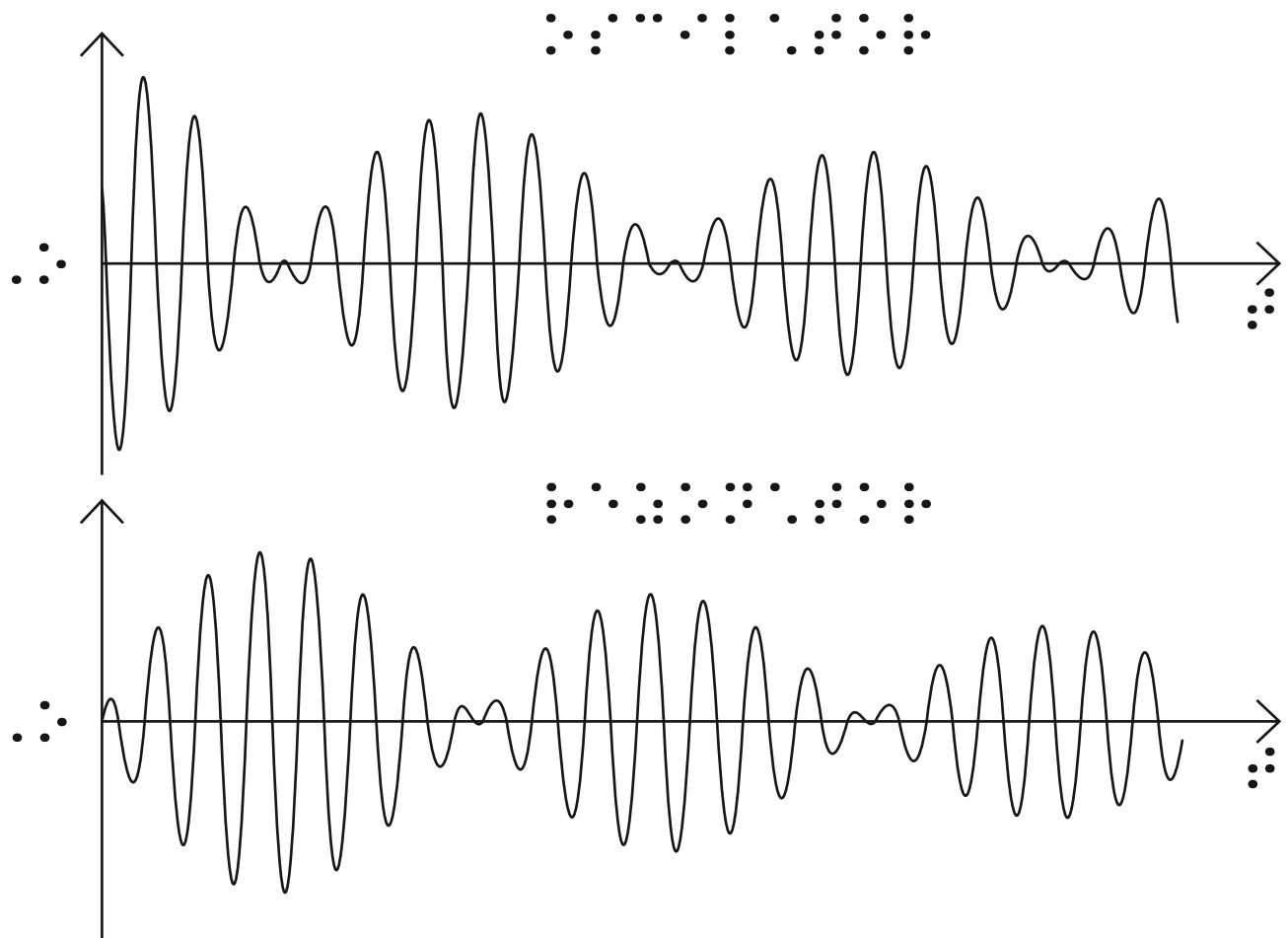
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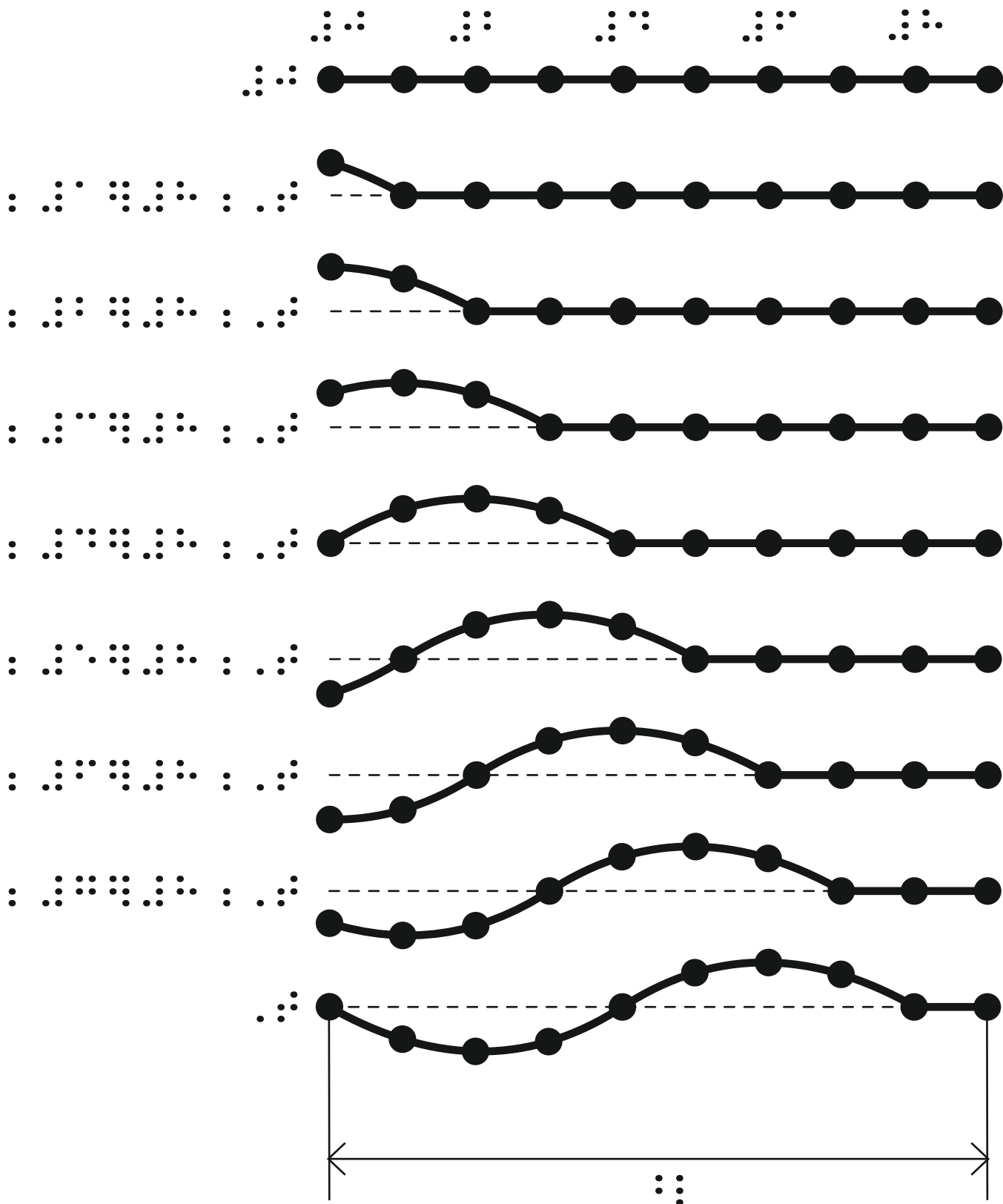


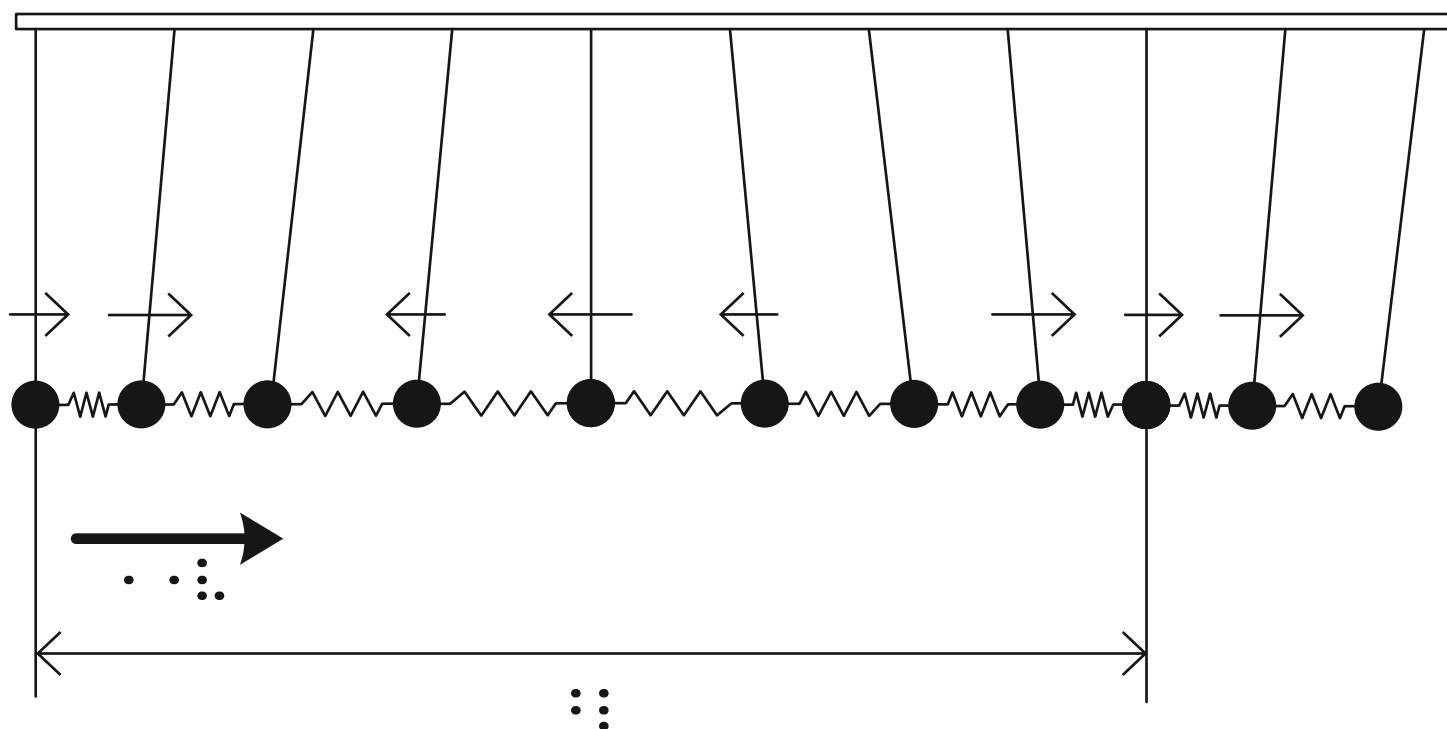
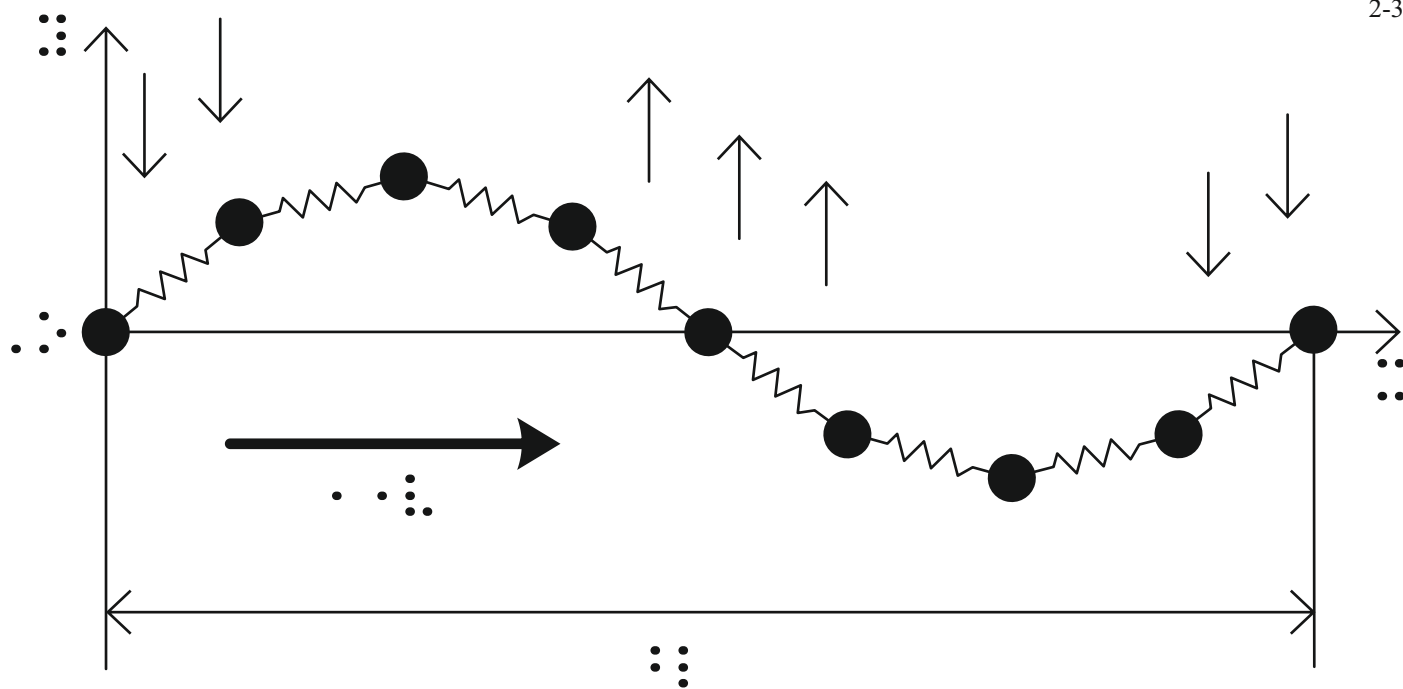
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1-31

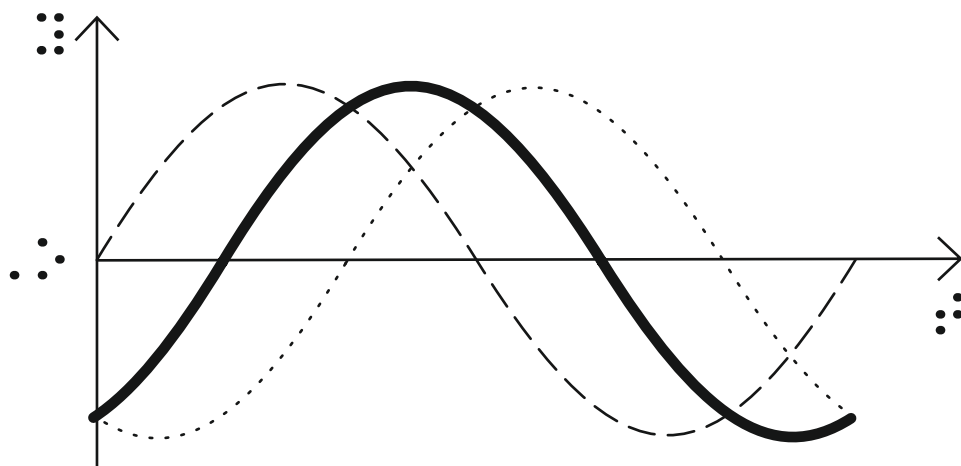
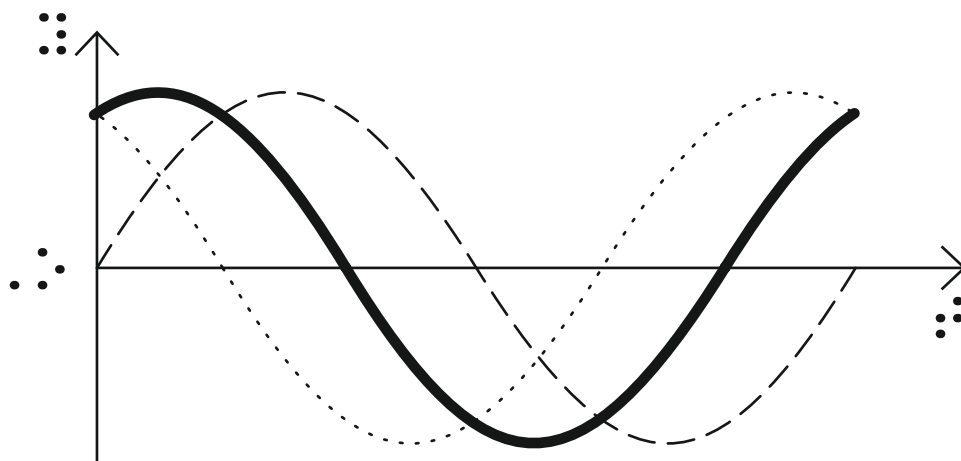


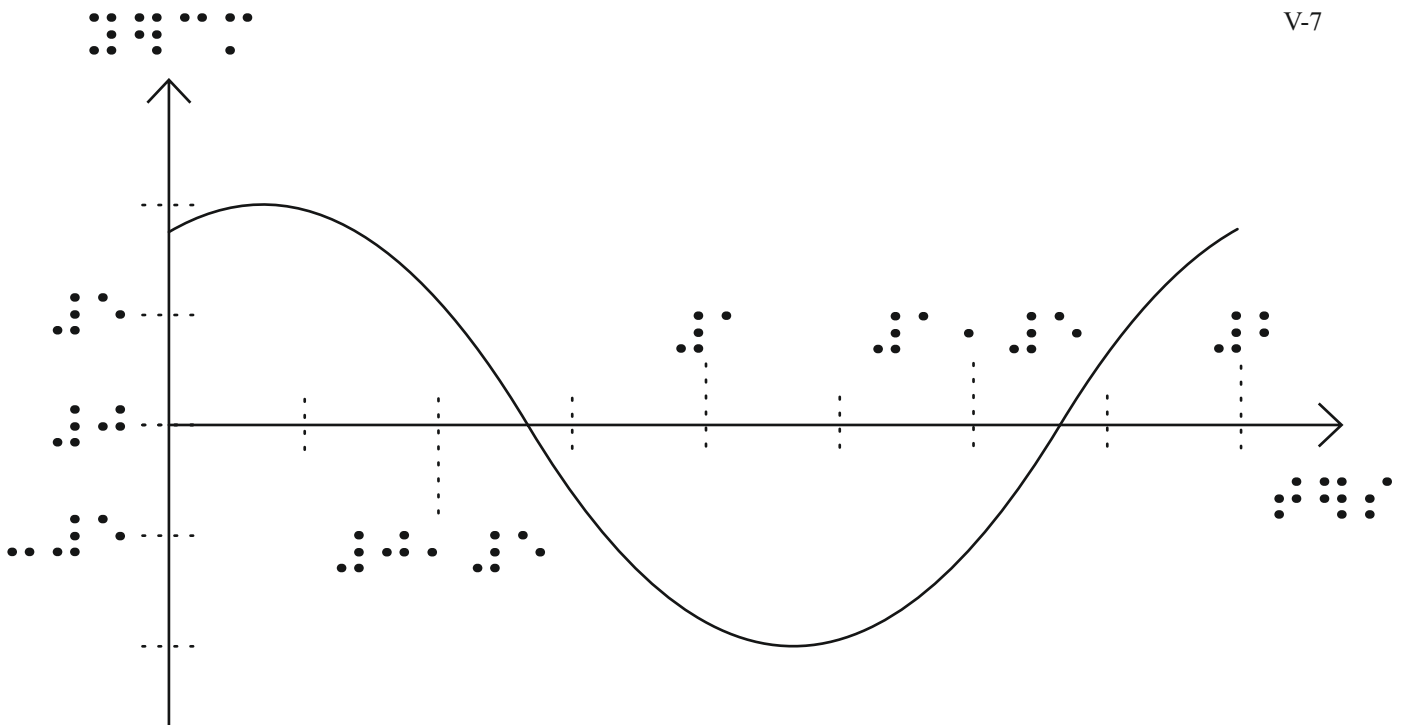
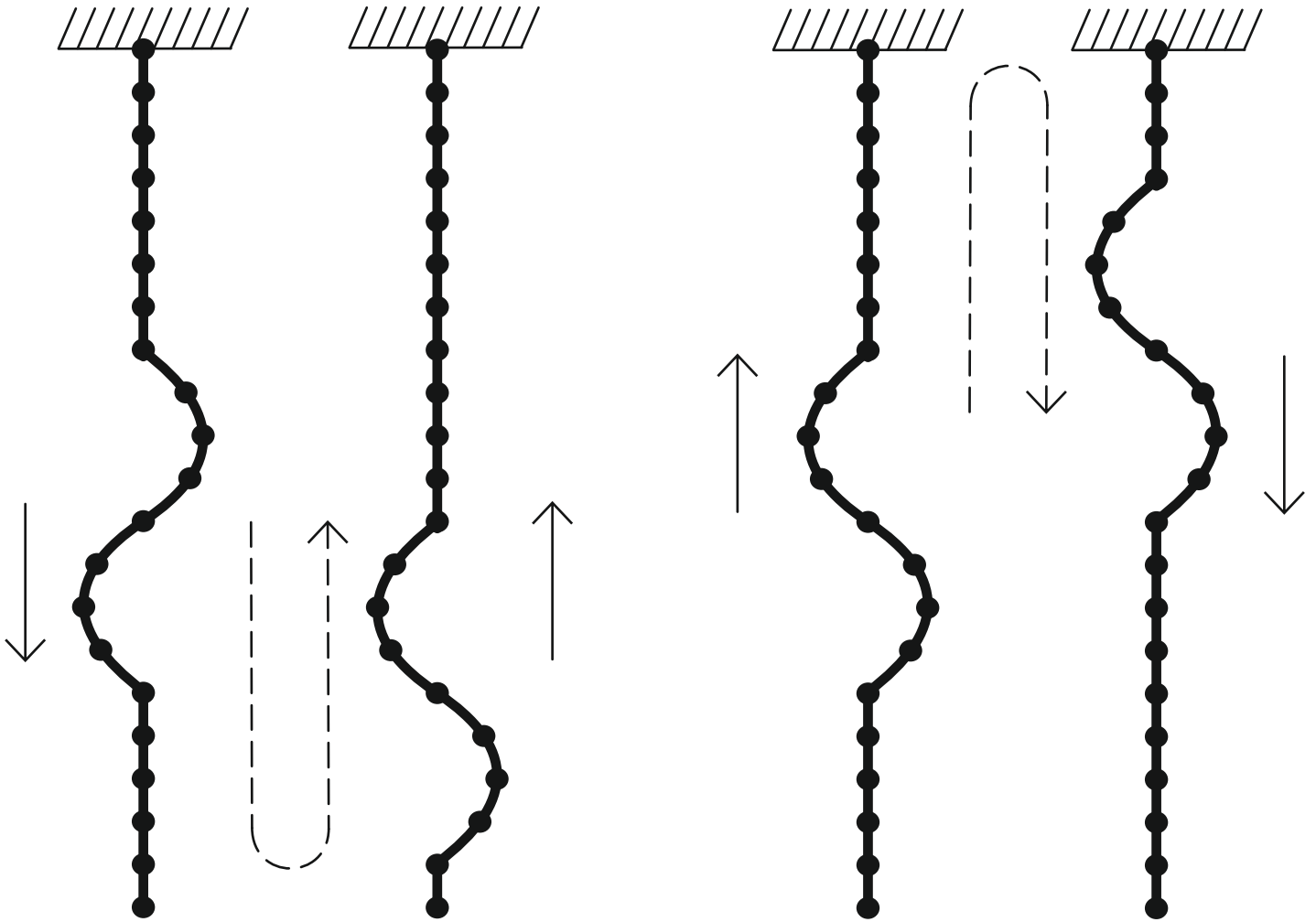
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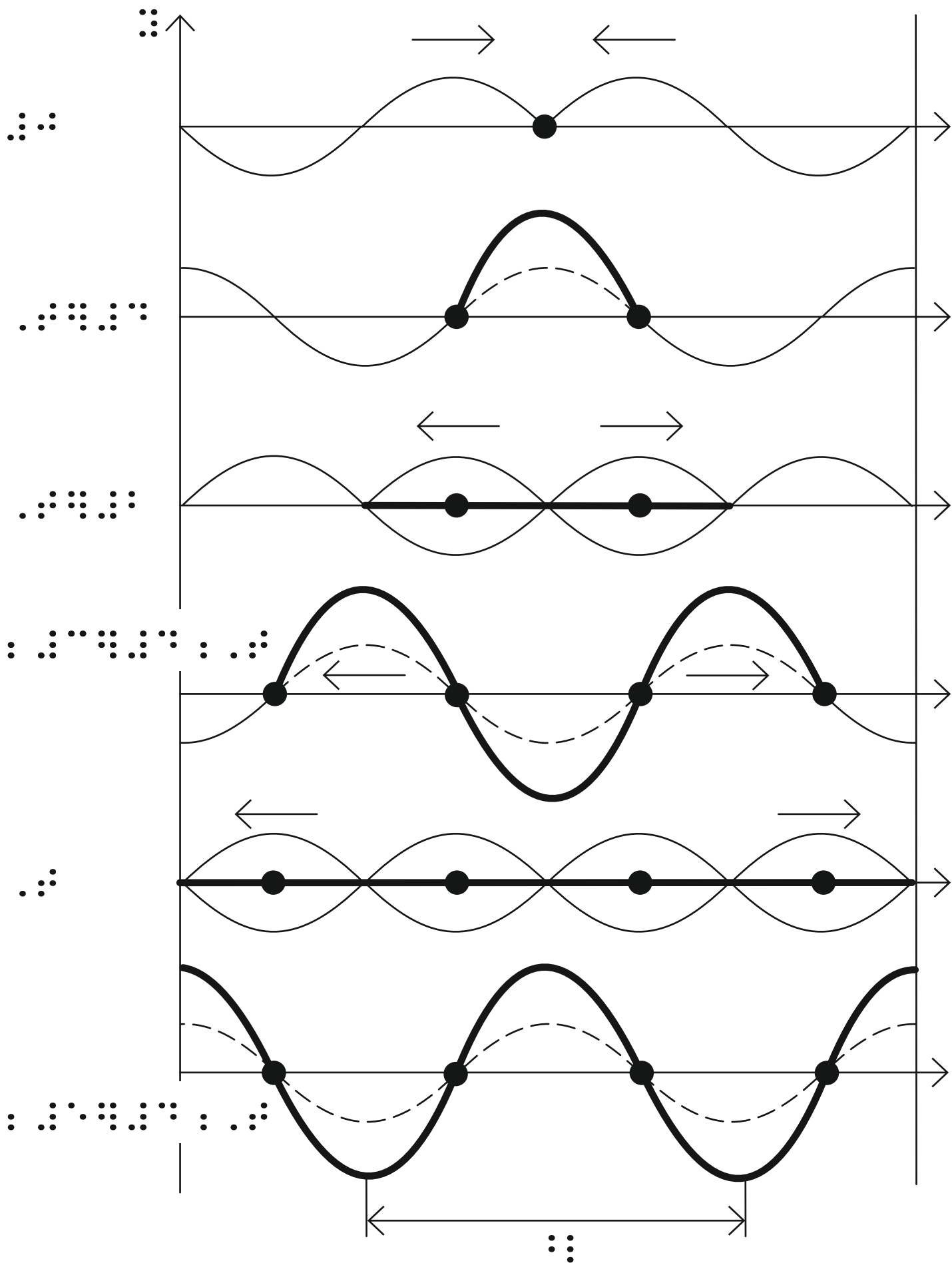




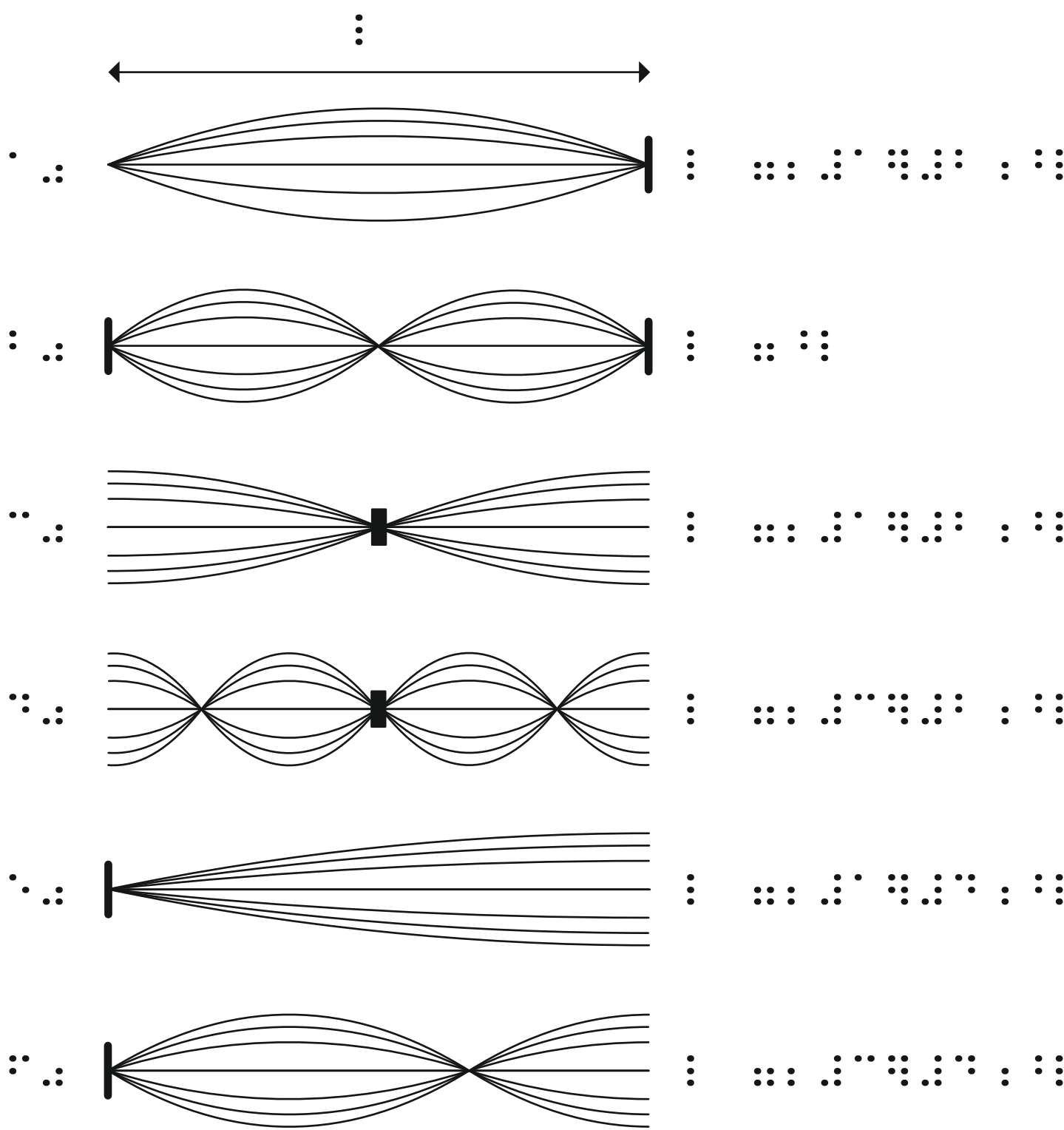
C1-3

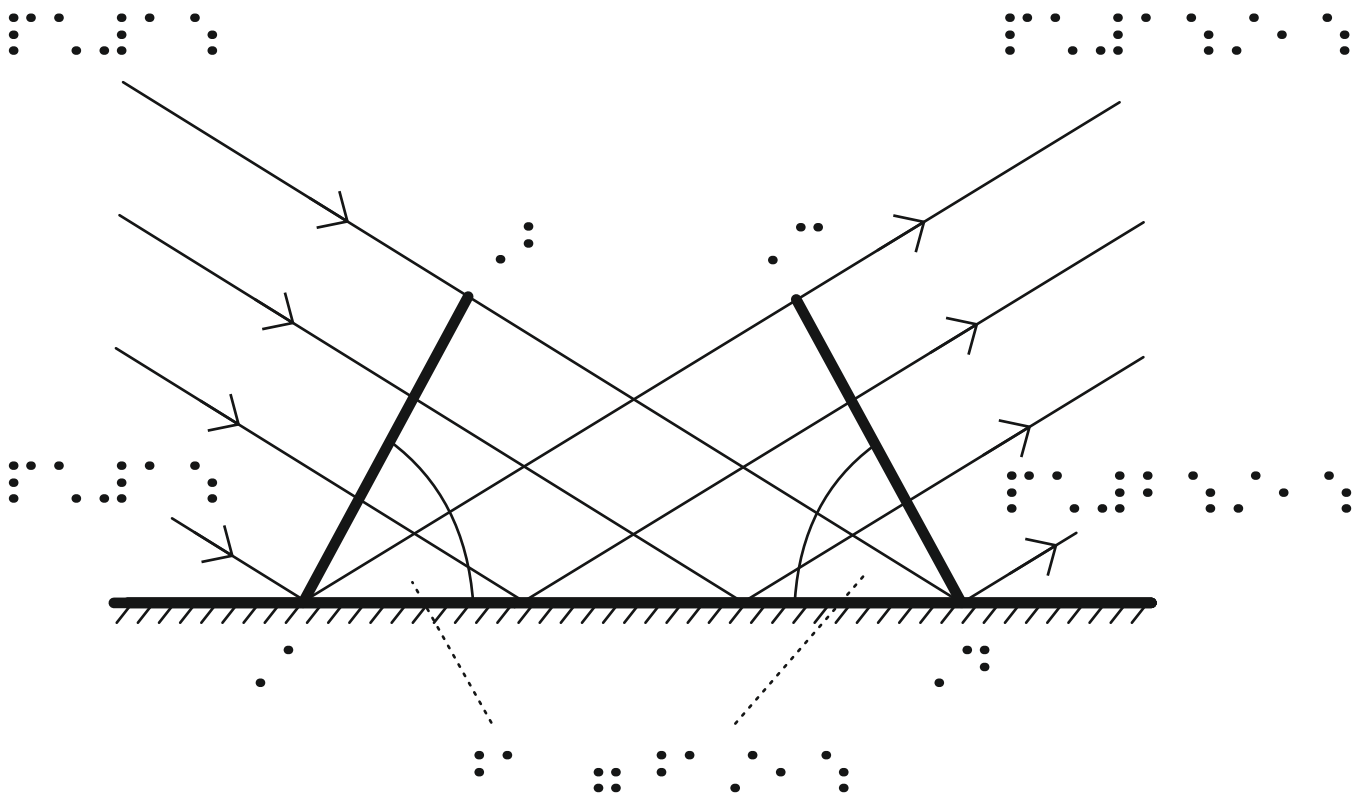
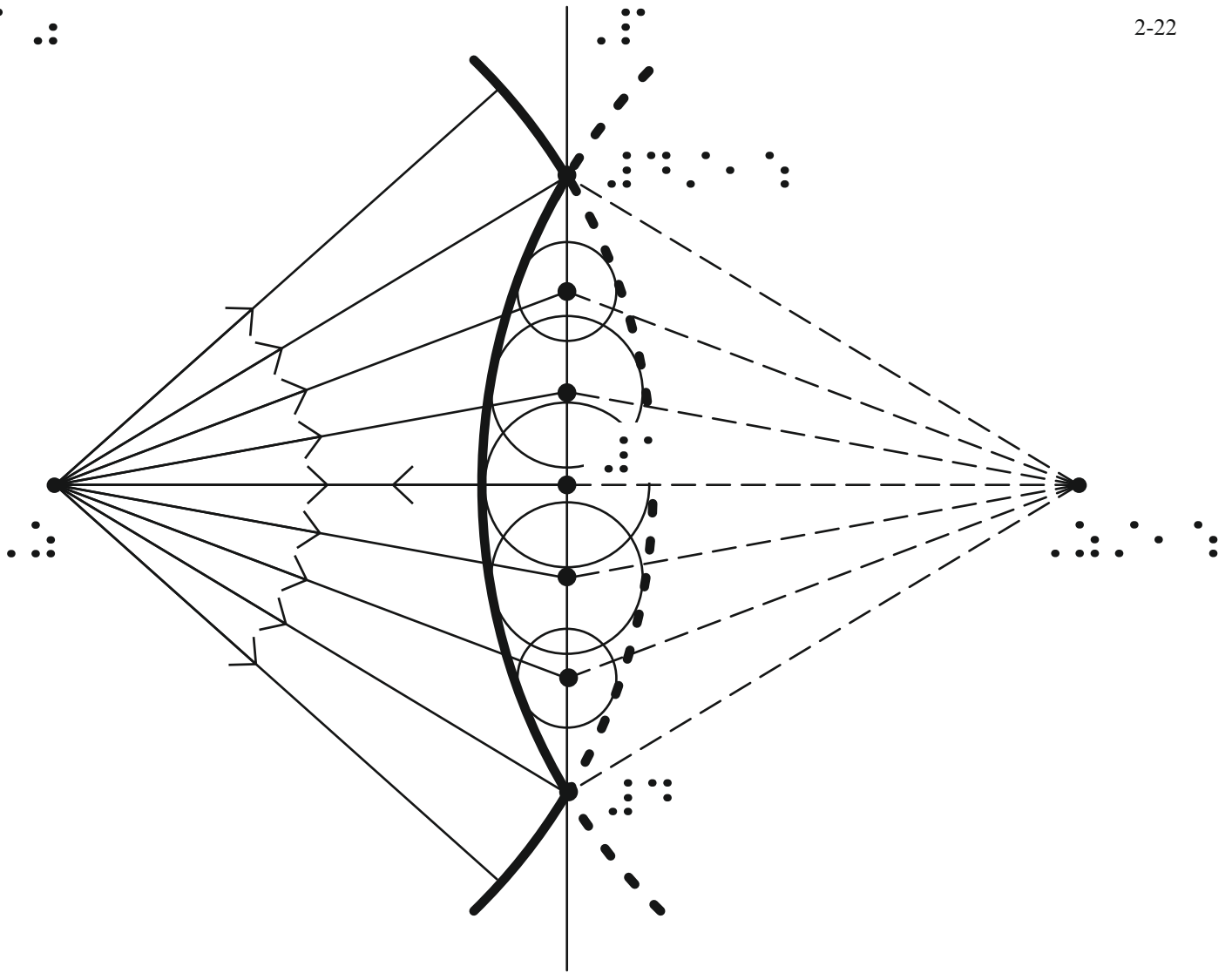


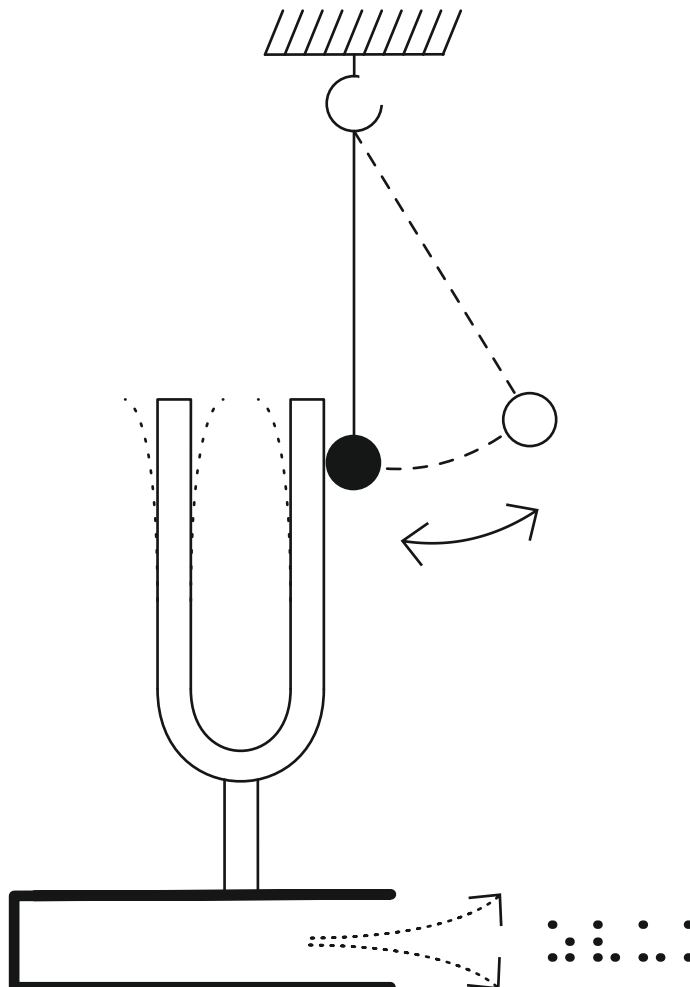
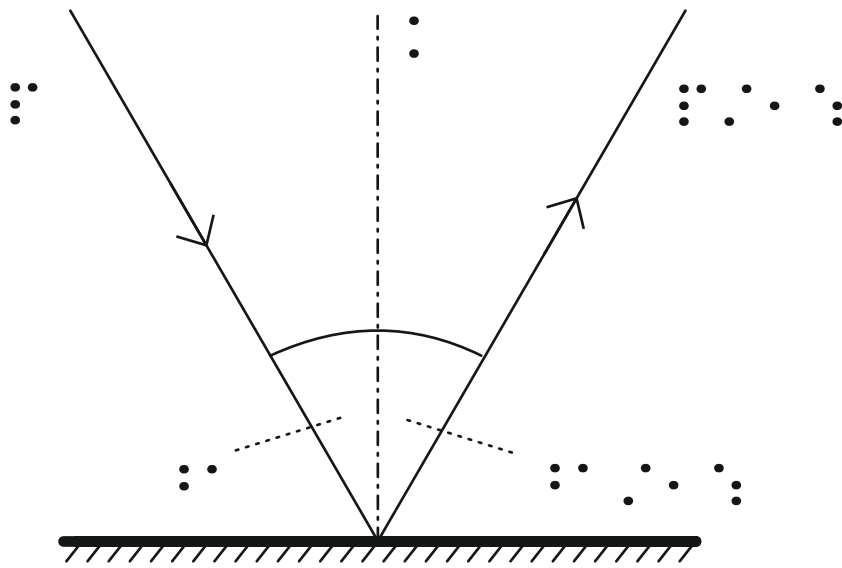




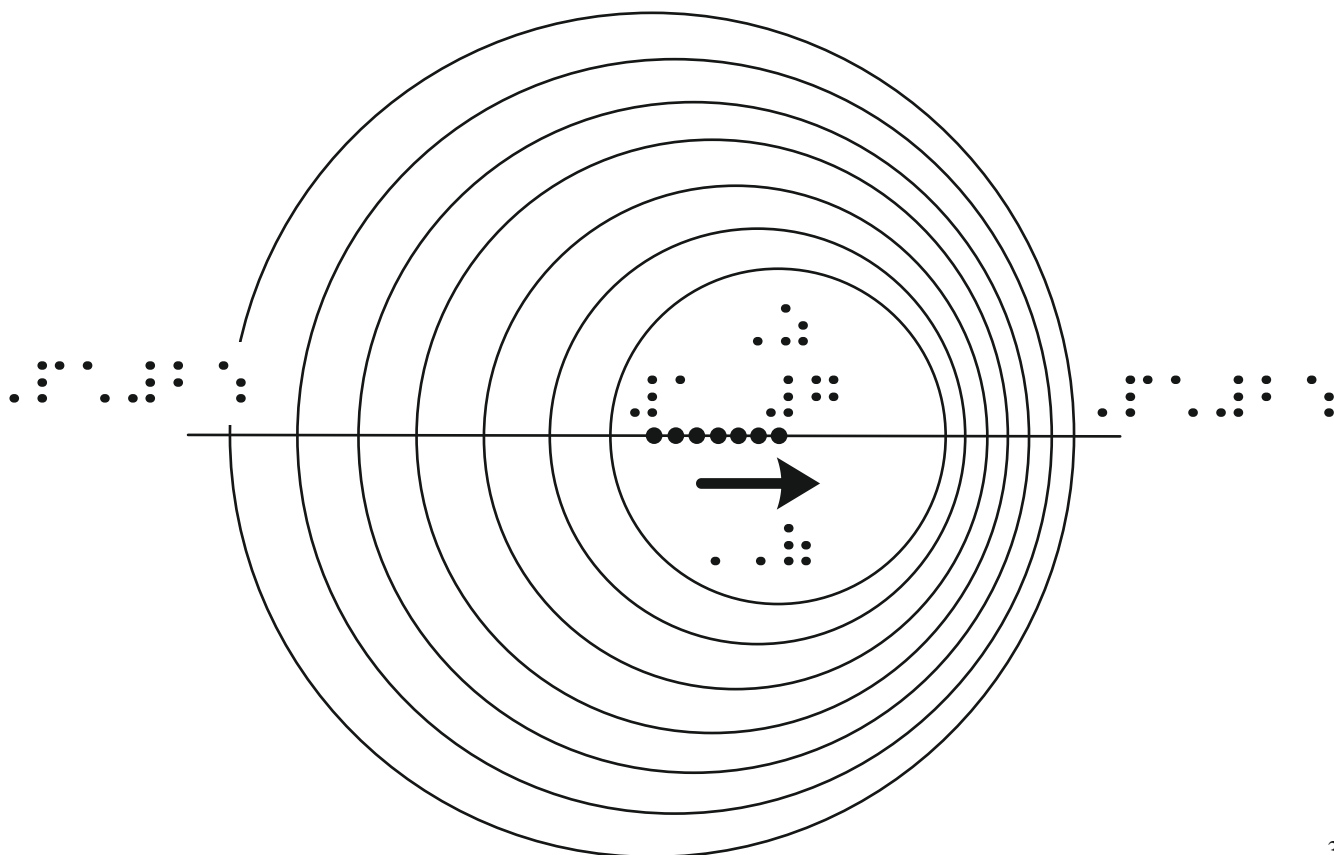
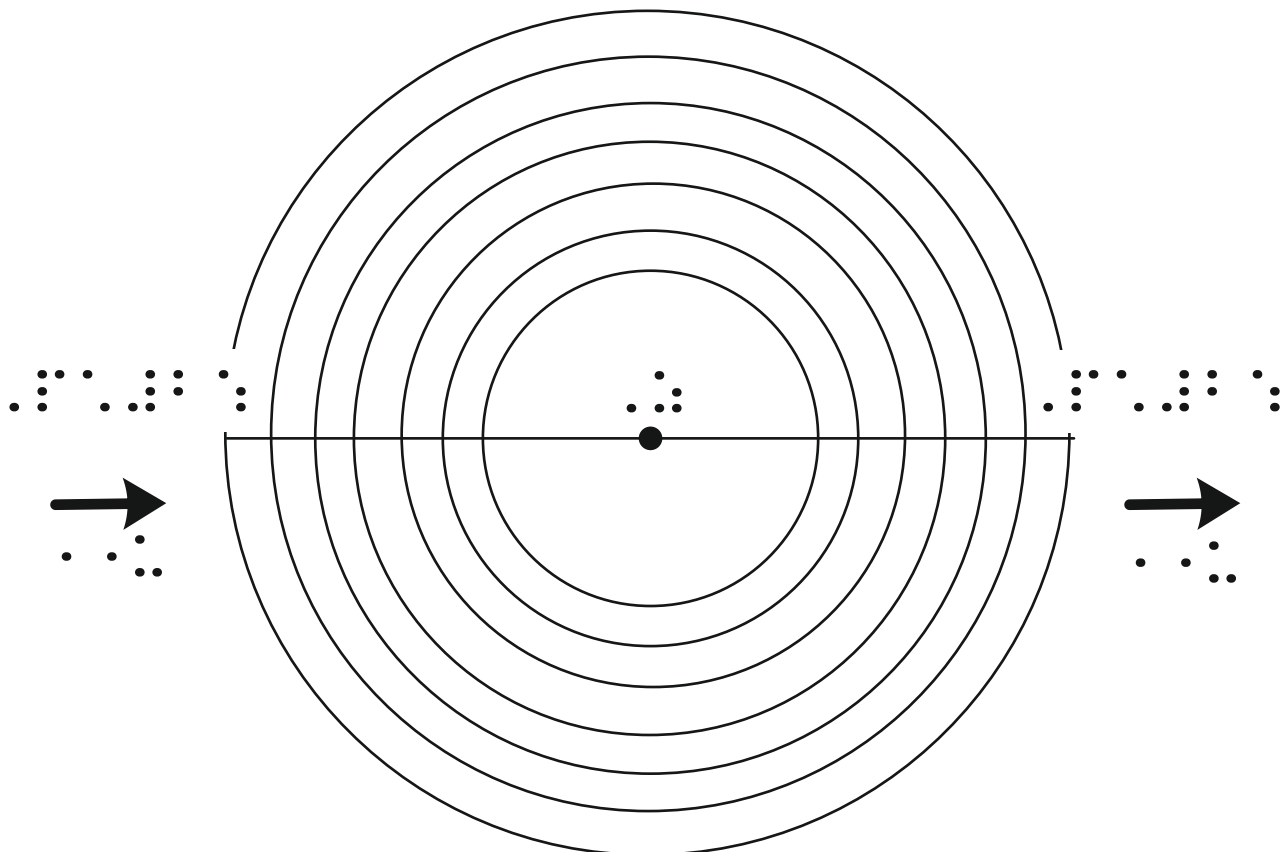
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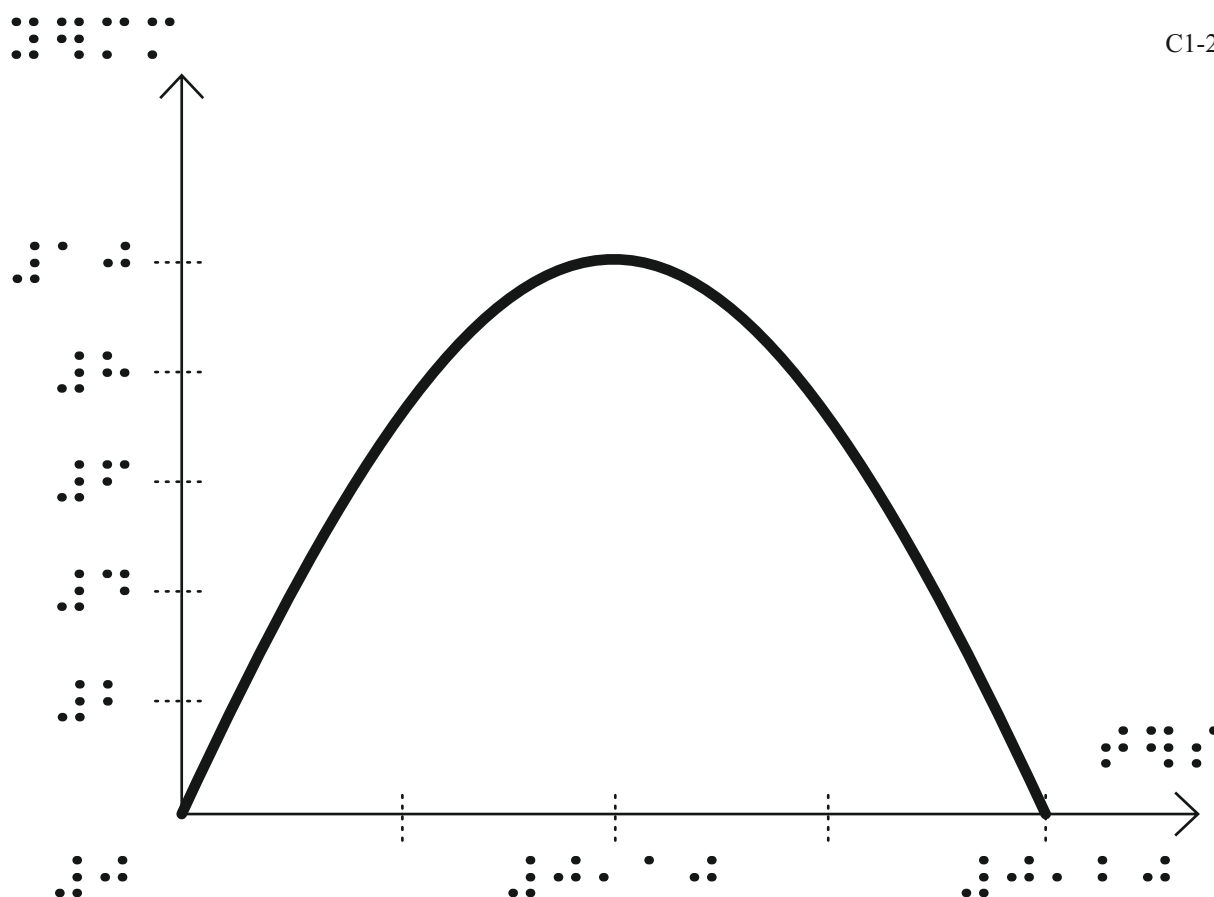
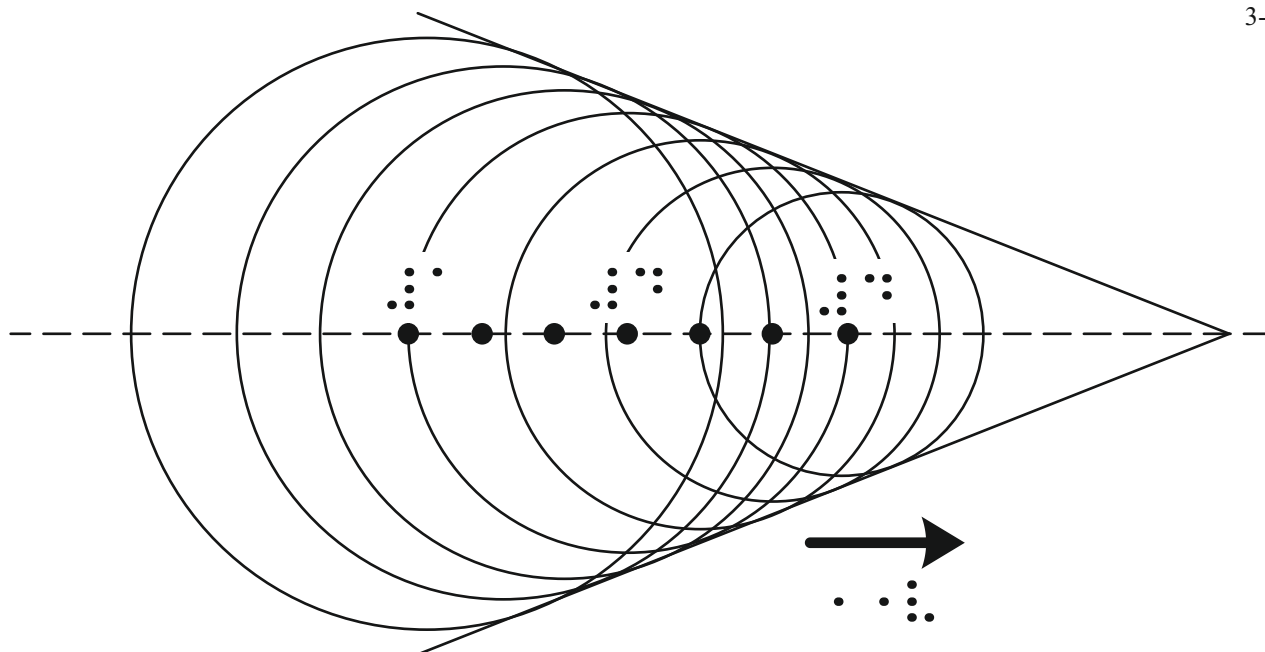


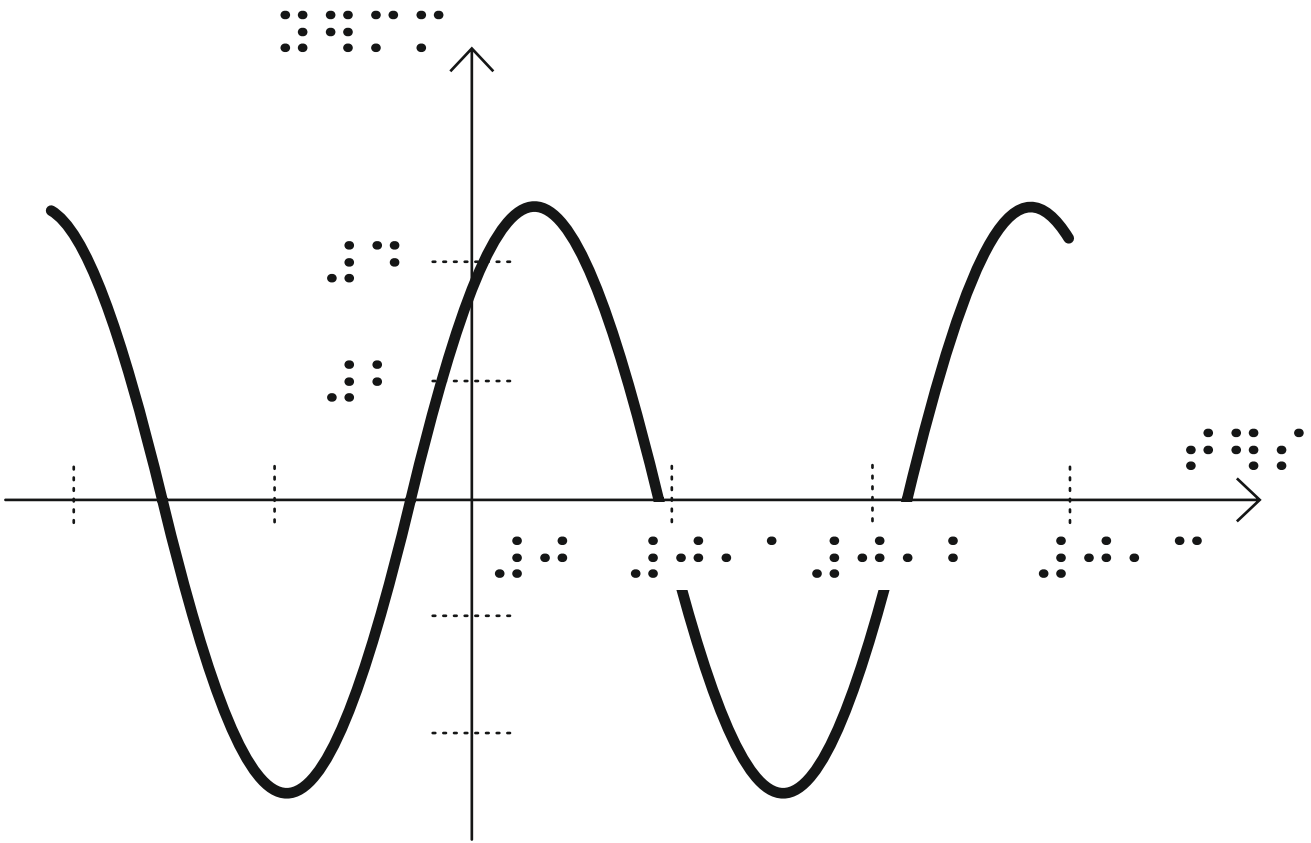




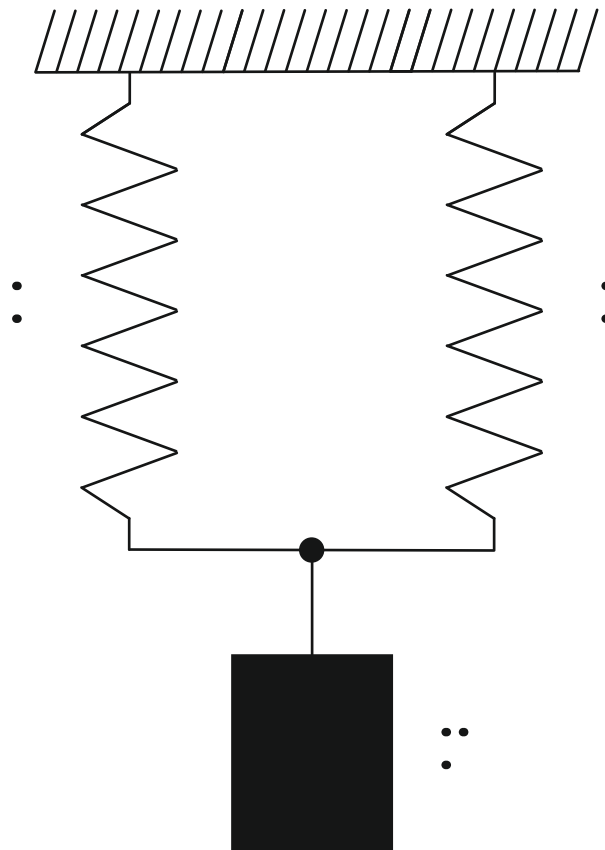
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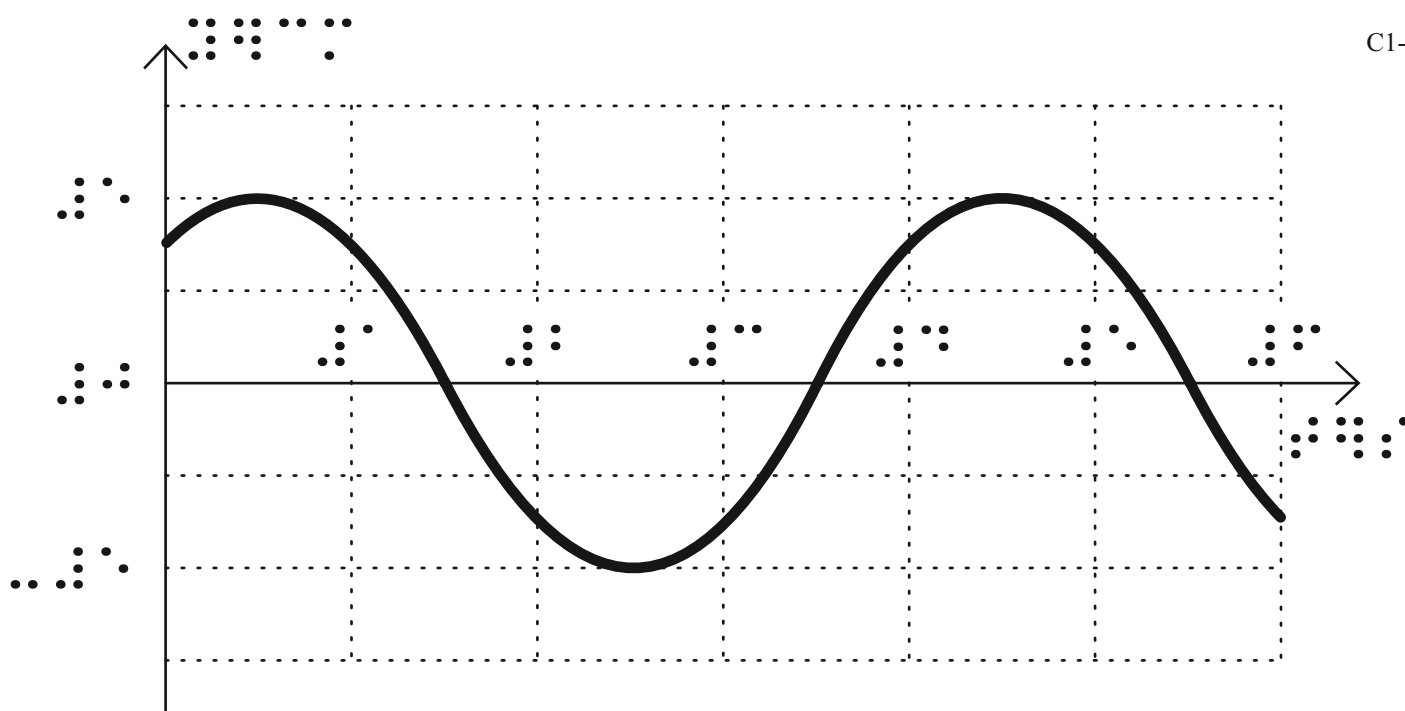
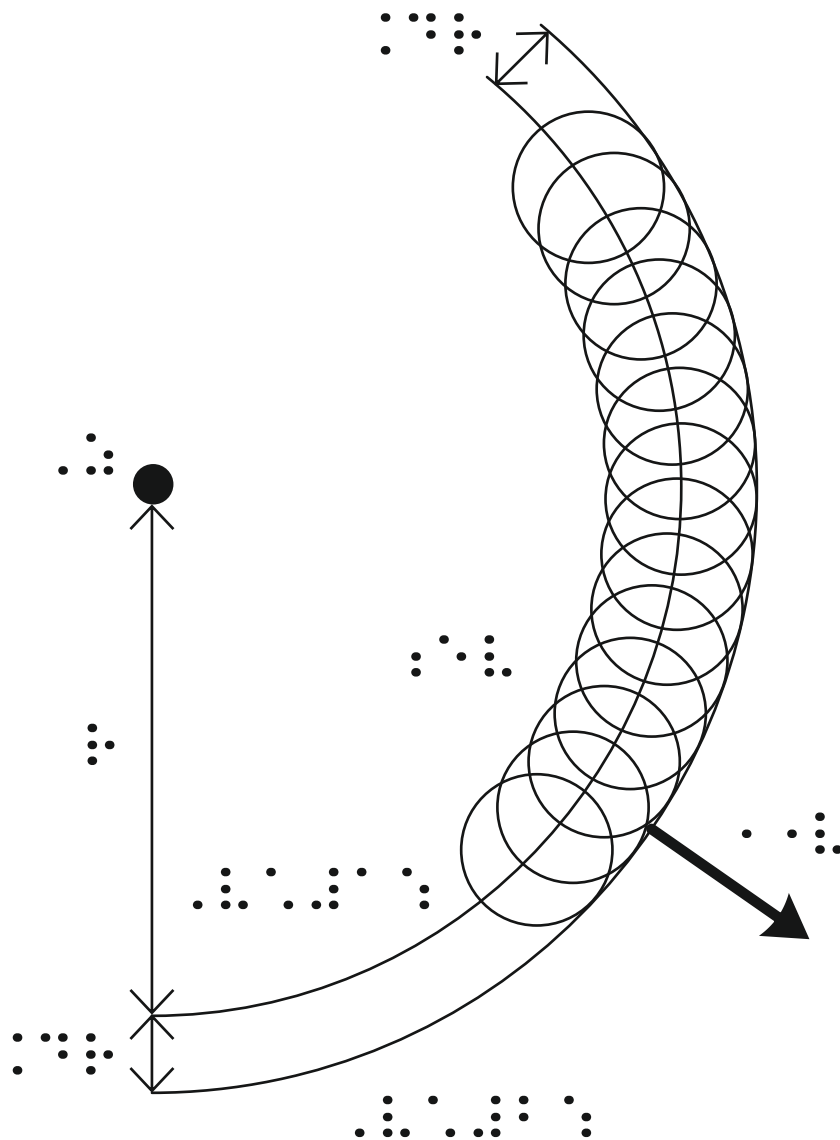






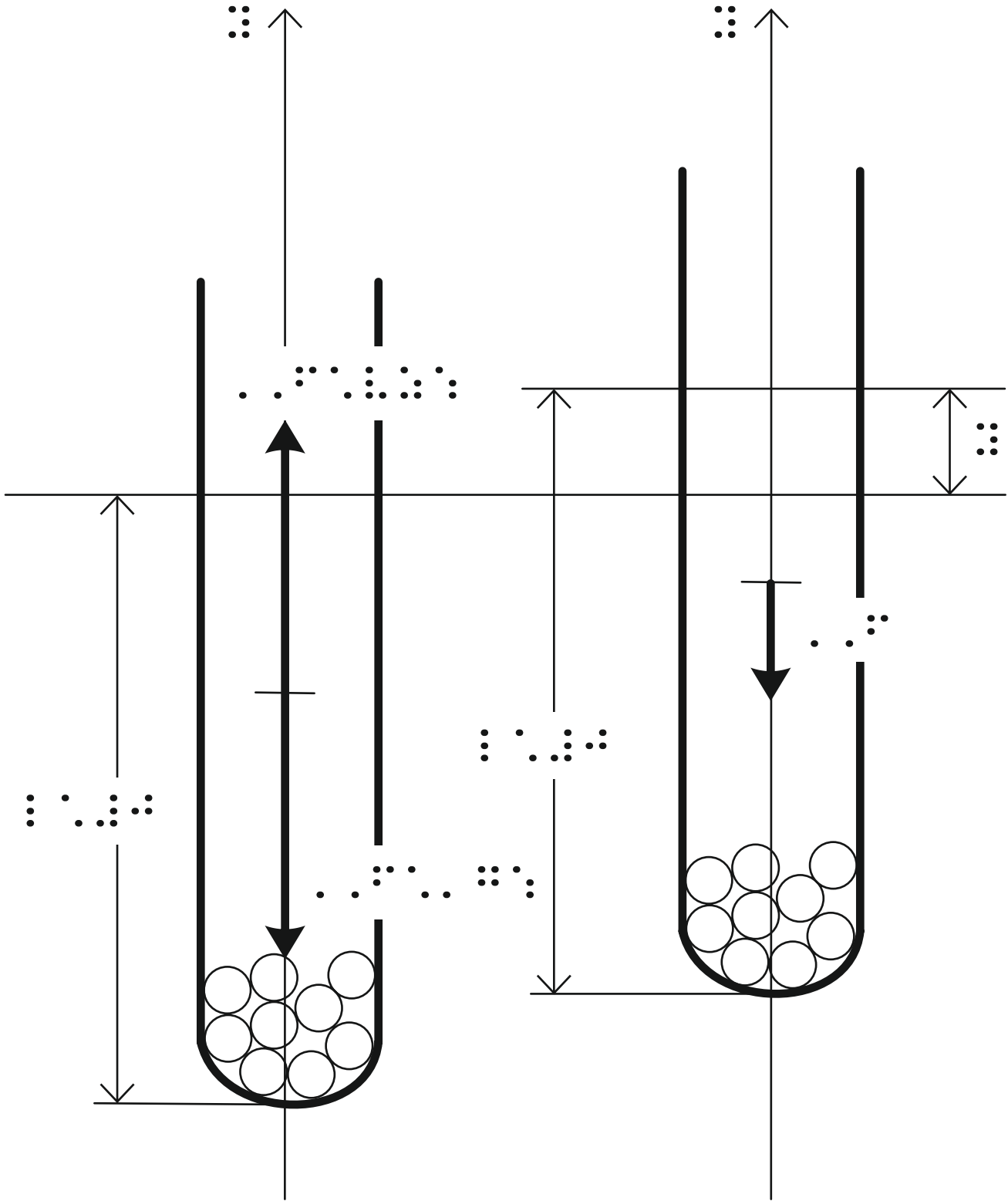
C2-4





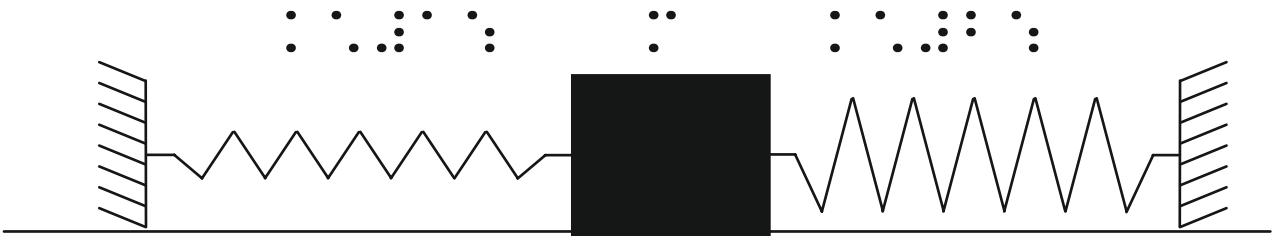
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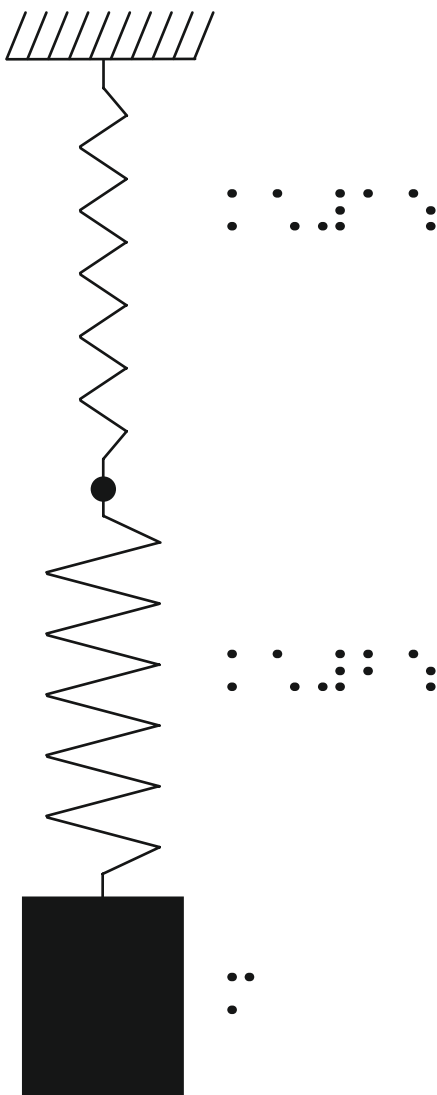


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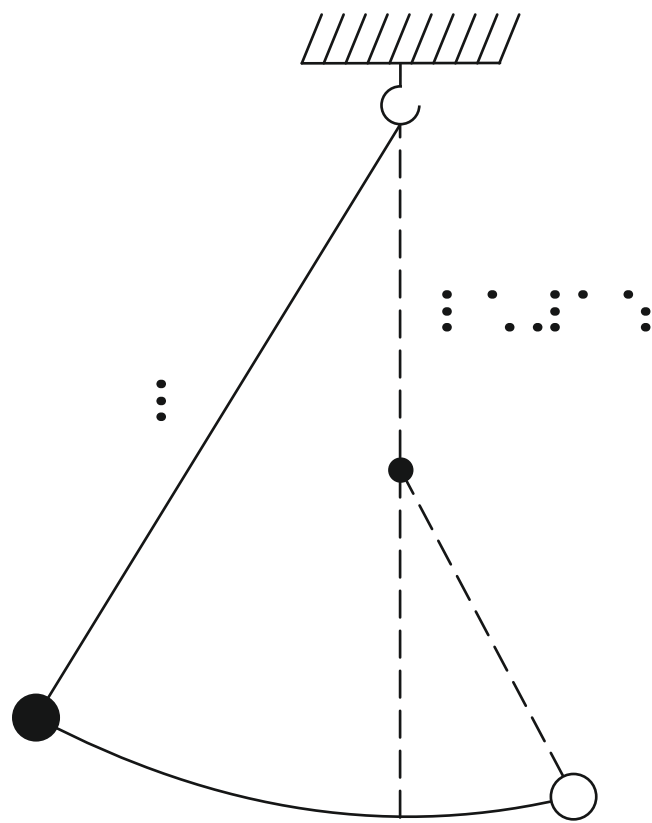
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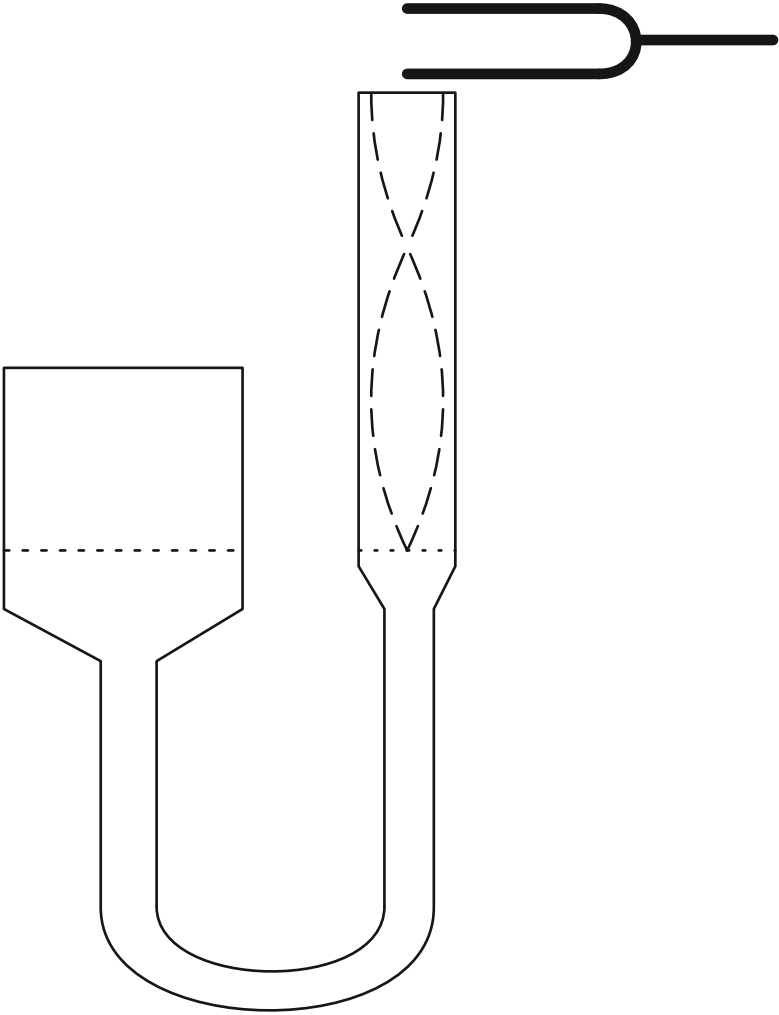
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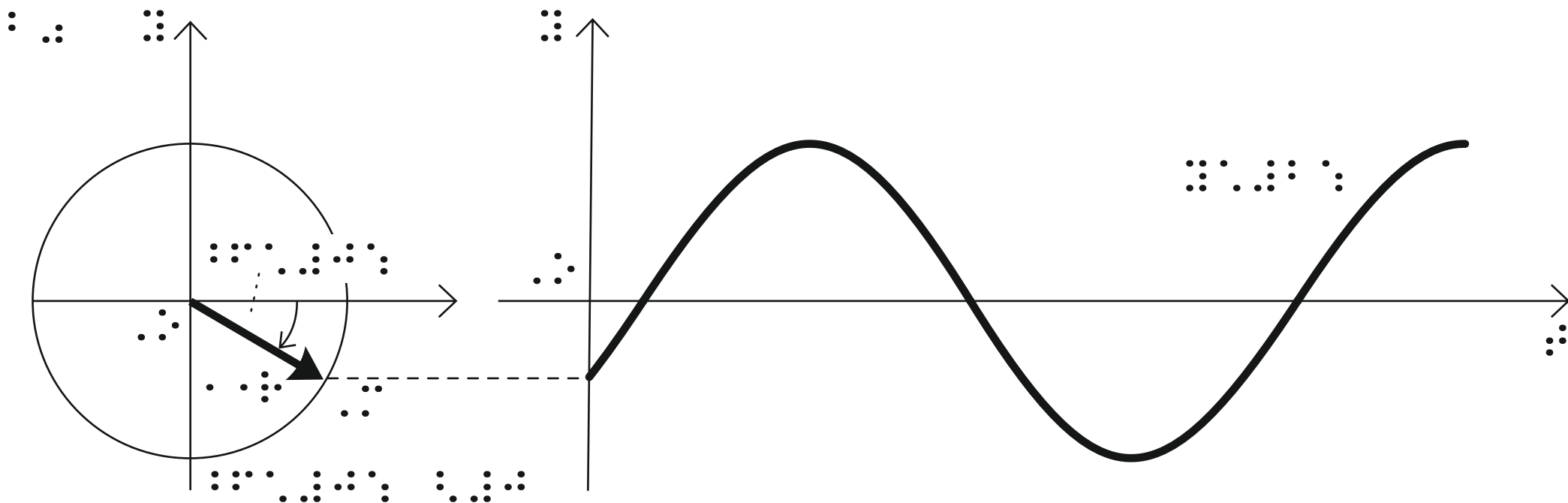
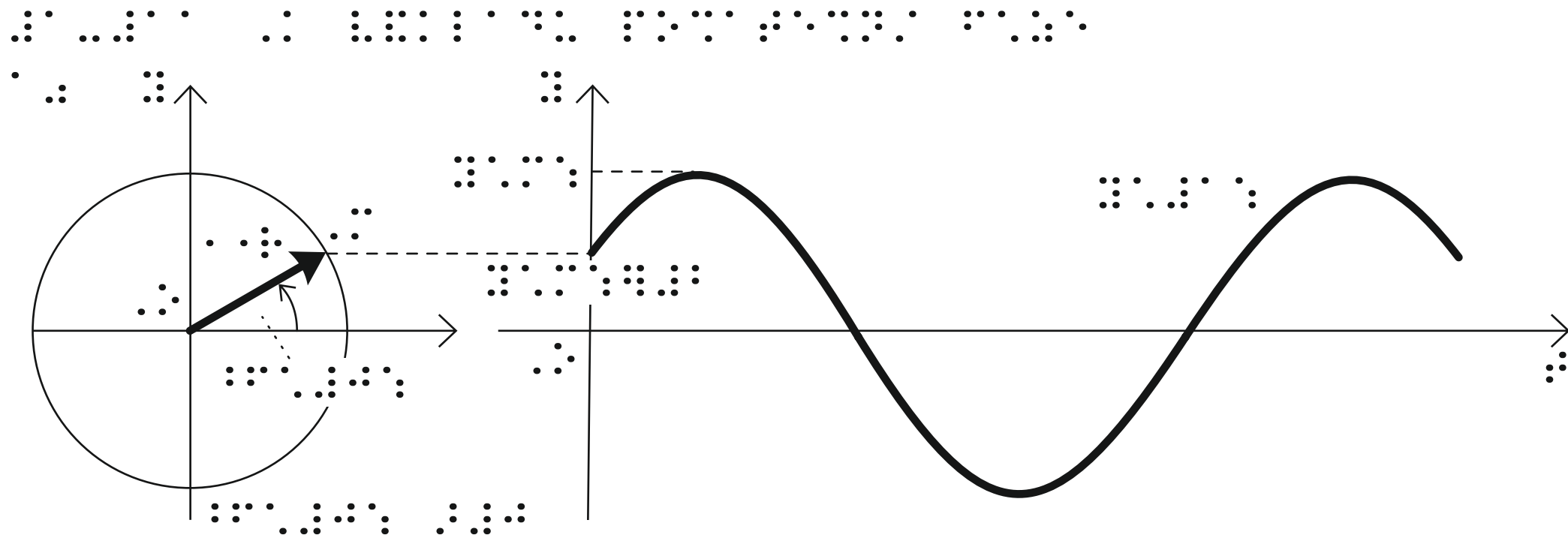


C2-5

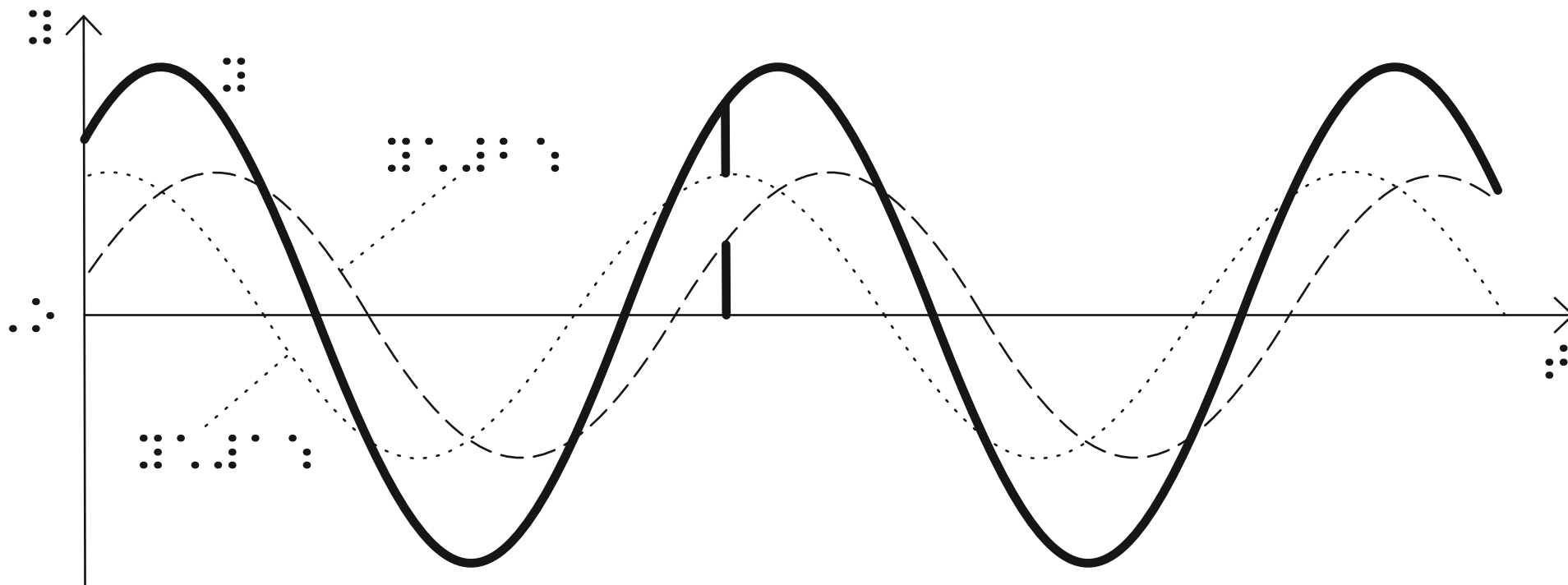


C3-2

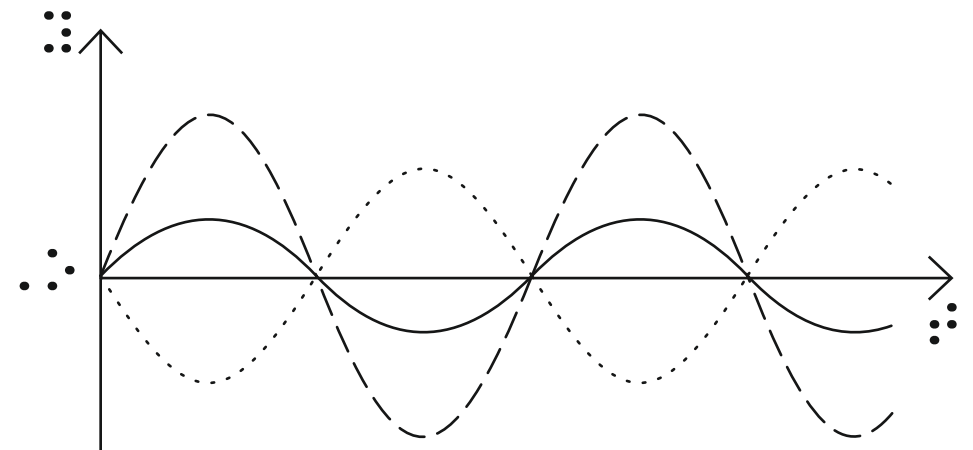
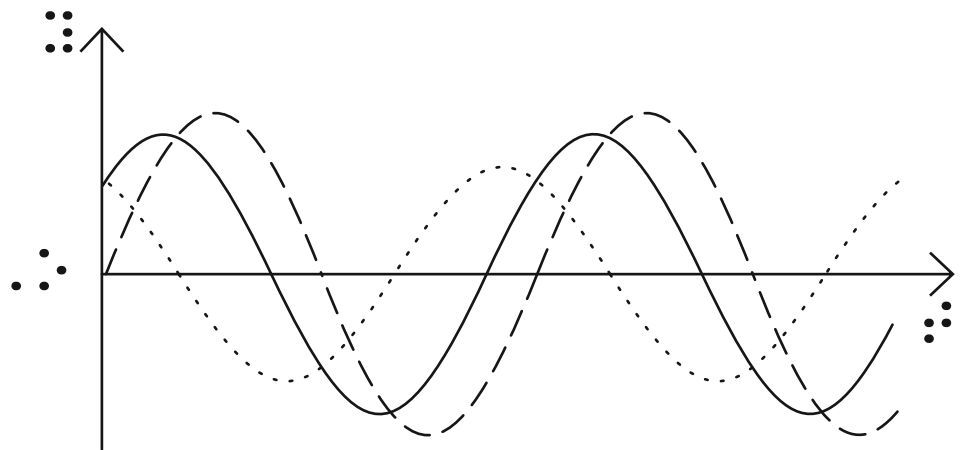
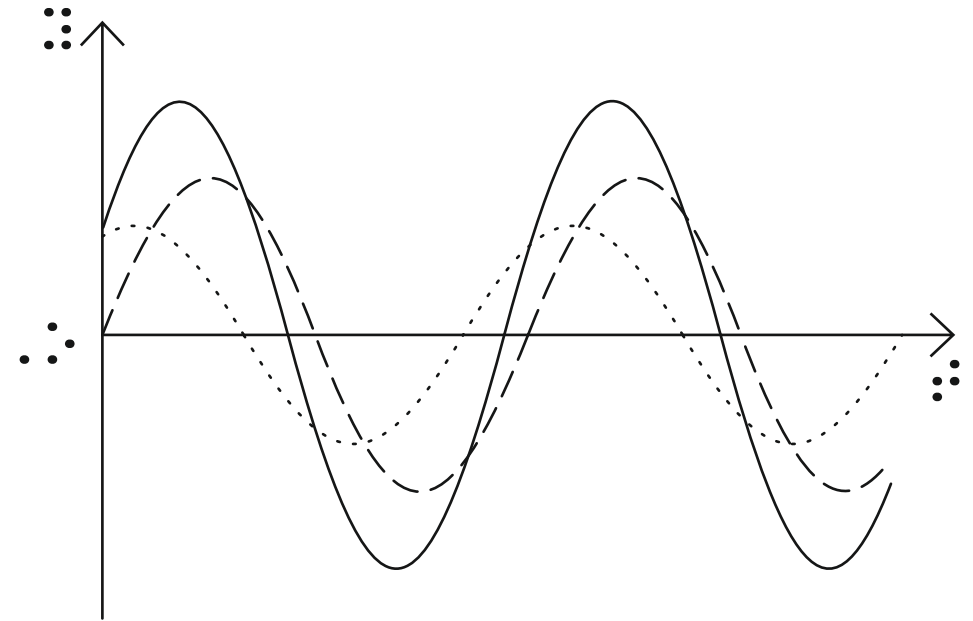
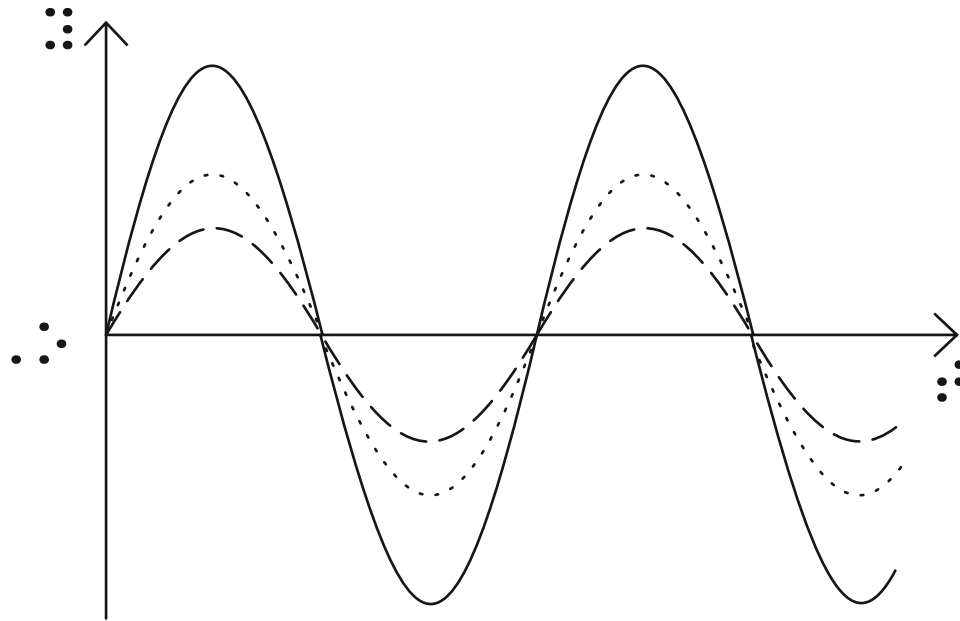




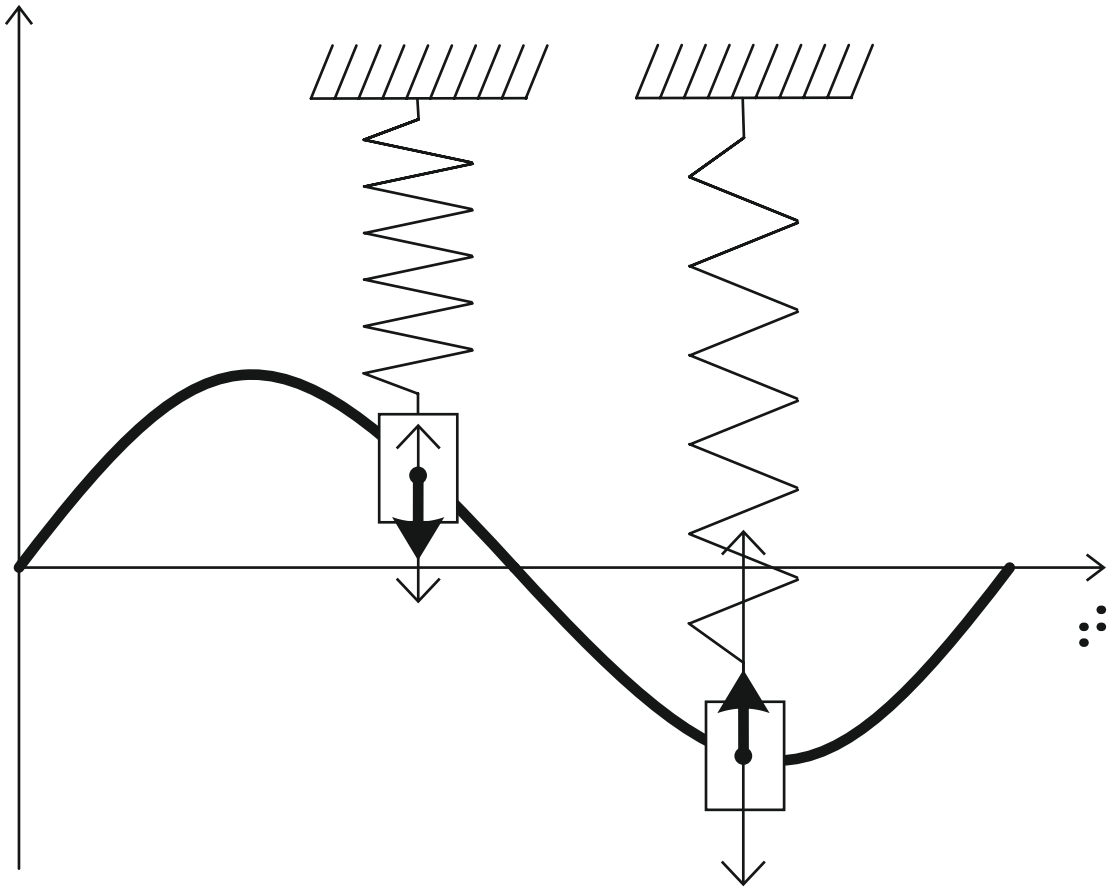
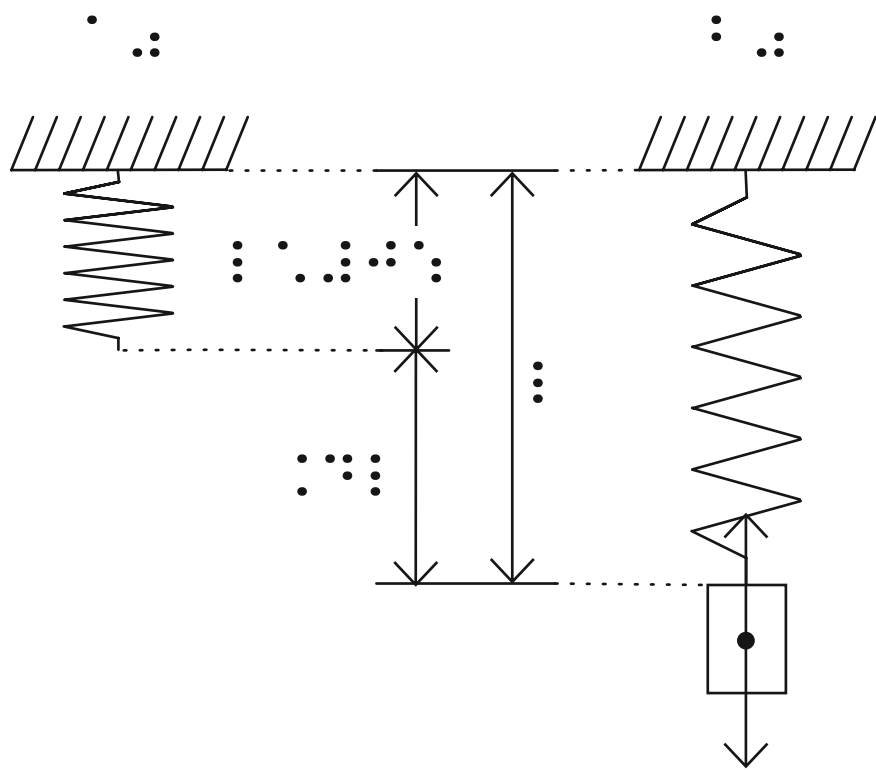
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1. 2. 3. 4. 5. 6. 7. 8. 9. 10. 11. 12. 13. 14. 15. 16. 17. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100.



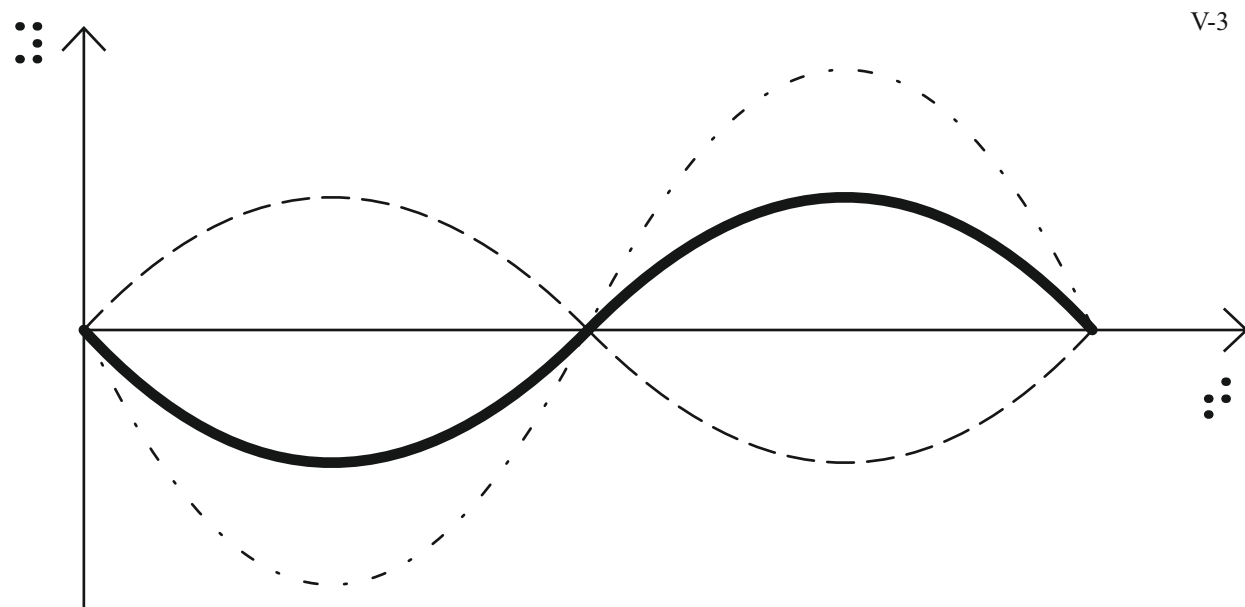
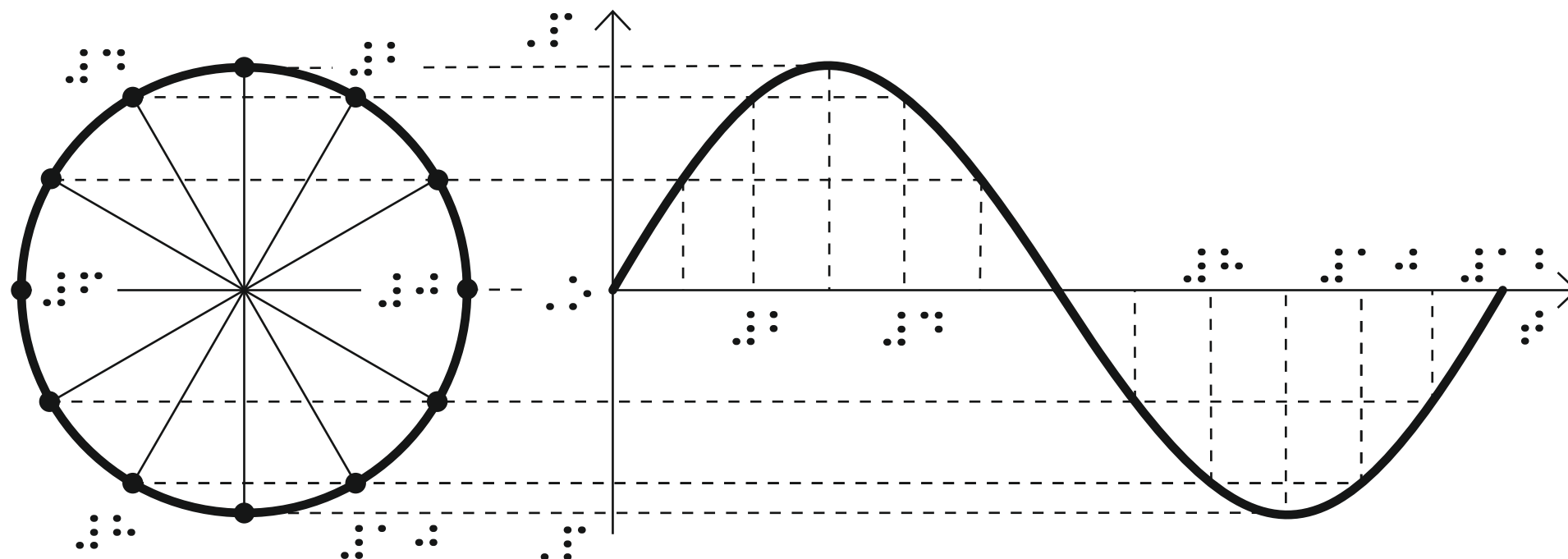
1. The system is a mass-spring-damper system. The mass is m , the spring constant is k , and the damping coefficient is c . The displacement from the equilibrium position is $x(t)$. The equation of motion is given by:

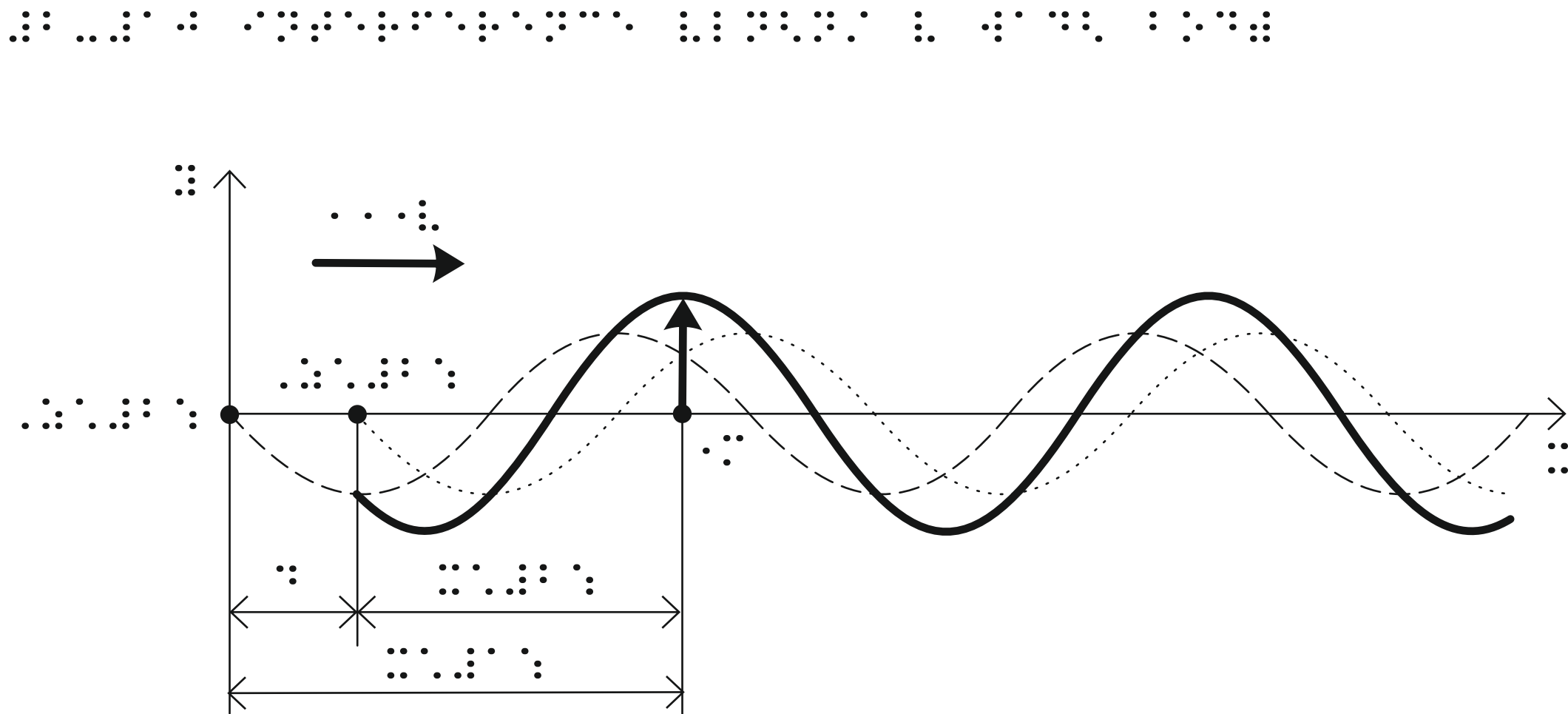
$$m\ddot{x} + c\dot{x} + kx = F(t)$$


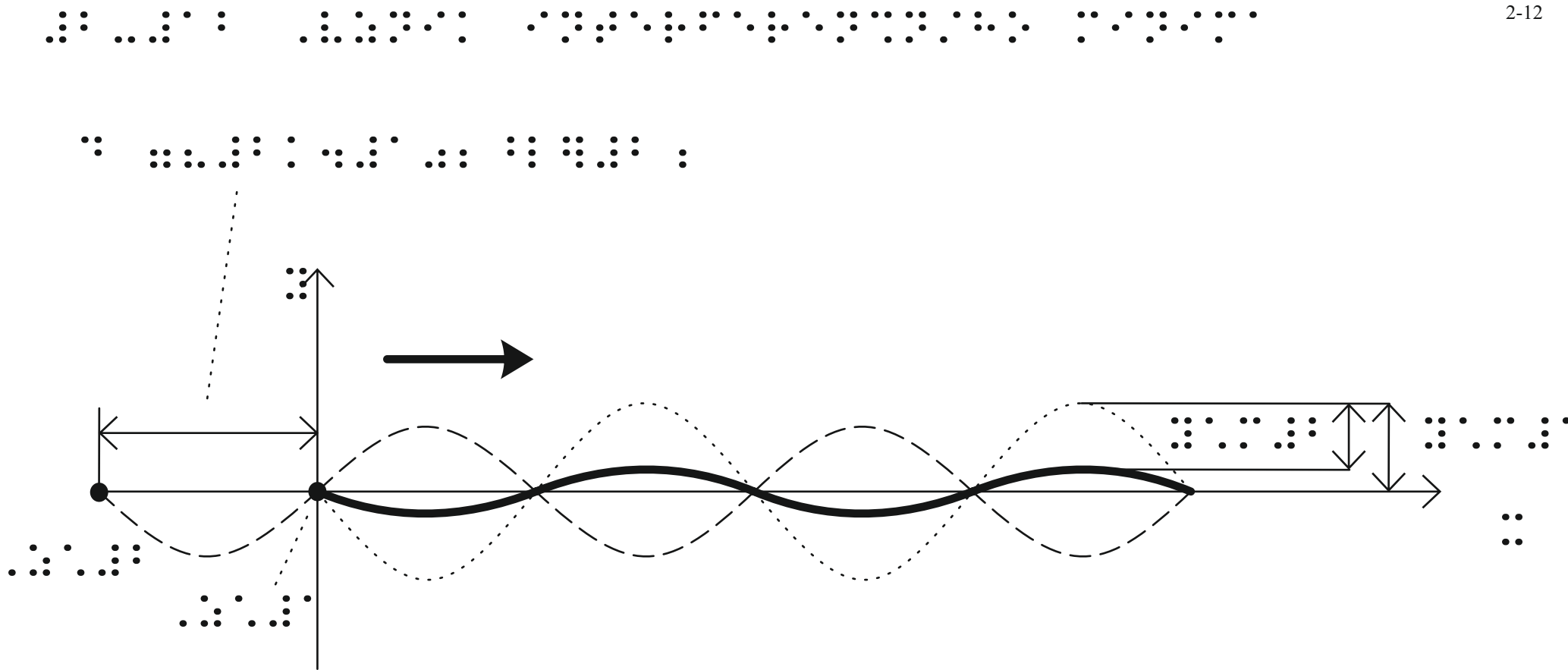
2. The system is a mass-spring-damper system. The mass is m , the spring constant is k , and the damping coefficient is c . The displacement from the equilibrium position is $x(t)$. The equation of motion is given by:

$$m\ddot{x} + c\dot{x} + kx = F(t)$$

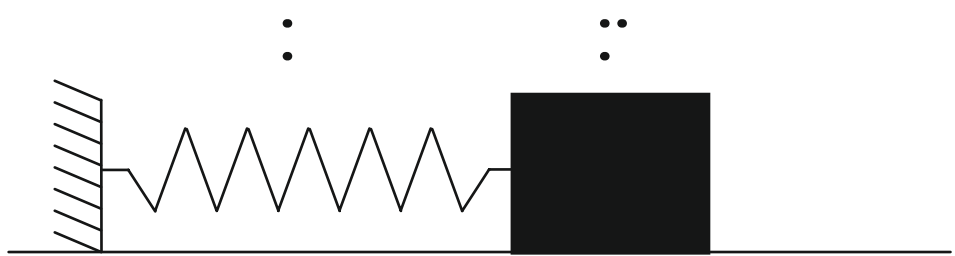
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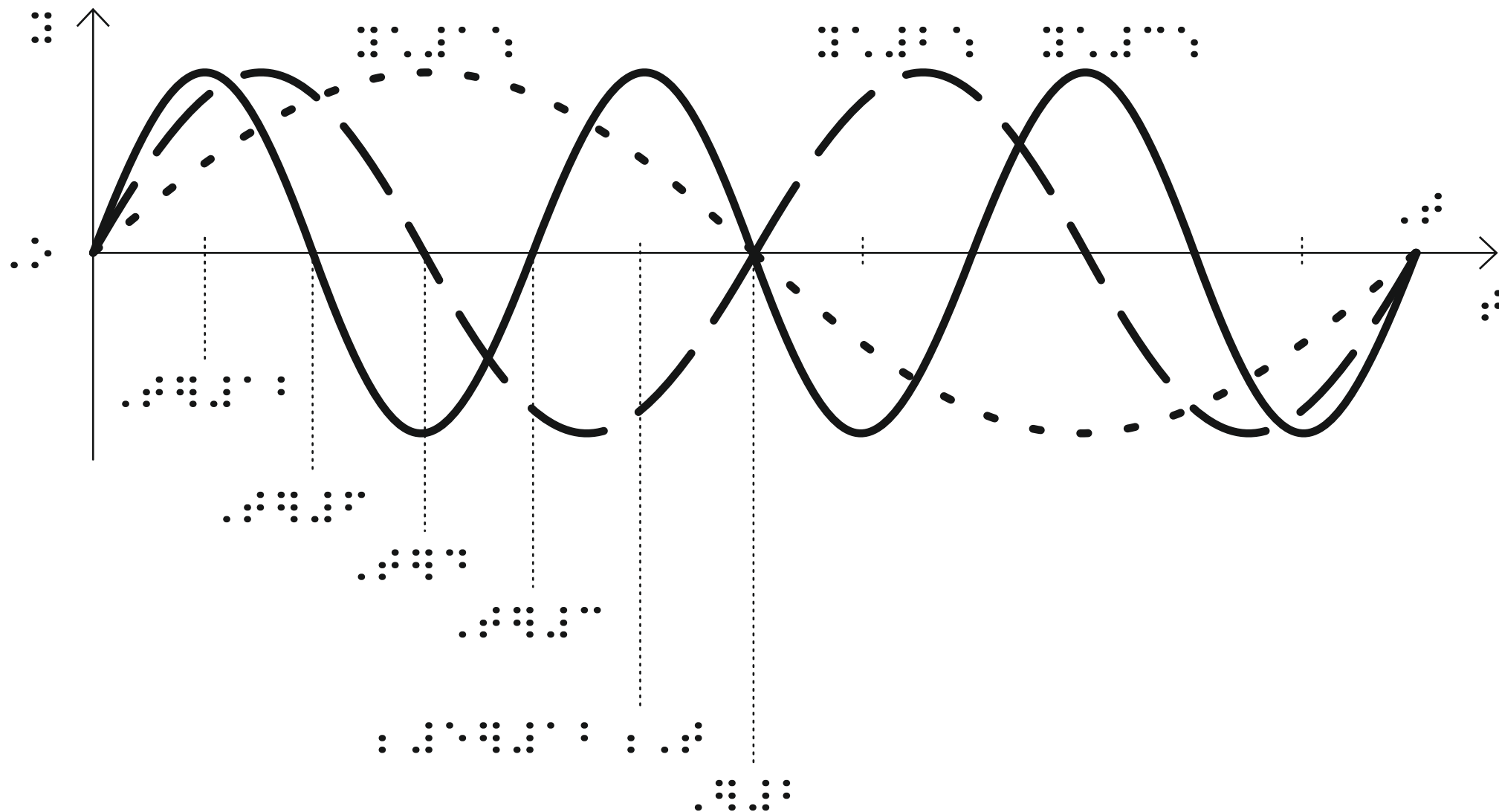




C2-3



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